

**Two phase designs  
with data missing by design:  
inverse probability weighted estimators;  
adjustments and improvements**



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Based on joint work with:

- Norman Breslow
- Takumi Saegusa

and

- 2011 ISI Review paper: Lumley, Shaw, Dai

# Outline

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- 1: Survey sampling: the Horvitz-Thompson estimator
- 2: Adjustments of the Horvitz-Thompson estimator:
  - ▶ Regression
  - ▶ Calibration
  - ▶ Estimated weights
- 3: The “paradox”
- 4: Parametric Models & Super-populations
- 5: Limit theory, part 1
- 6: Semiparametric Models & Super-populations
- 7: Limit theory, part 2
- 8: Problems and further questions

# Outline

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- Part I: Sections 1-4. Based on Thomas Lumley, Pamela Shaw, and James Dai (2011). Connections between survey and calibration estimators and semiparametric models for incomplete data. *Int. Statist. Rev.* **79**, 200-220.
- Part II: Sections 5-8: Based on
  - ▶ Norman Breslow and Jon A. W. (2007). *Scand. J. Statist.* **34**, 86-102.
  - ▶ Norman Breslow and Jon A. W. (2008). *Scand. J. Statist.* **35**, 83-103.
  - ▶ Takumi Saegusa and Jon A. W. (2011). Weighted likelihood estimators with calibration and estimated weights. *Manuscript in progress.*

# 1. Survey sampling: the Horvitz-Thompson estimator

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- First consider a finite population

$$\{(x_i, y_i) : 1 \leq i \leq N\}$$

with  $y_i \in \mathbb{R}$ ,  $x_i \in \mathbb{R}^p$ .

- Suppose: the sampling probability  $\pi_i$  for each individual is known;  $R_i = 1$  if item  $i$  is sampled,  $R_i = 0$  if not, and

$$P(R_i = 1) = \pi_i, \quad i = 1, \dots, N.$$

- Bernoulli (independent) sampling: the  $R_i$ 's are independent, with  $P(R_i = 1) = n/N$  for  $i = 1, \dots, N$  with  $1 < n < N$ . Thus

$$P(R_1 = r_1, \dots, R_N = r_N) = \left(\frac{n}{N}\right)^{\sum_1^N r_i} \left(1 - \frac{n}{N}\right)^{N - \sum_1^N r_i}$$

for  $r_i \in \{0, 1\}$ . Note that  $\sum_1^N R_i \sim \text{Binomial}(N, n/N)$  is random.

# 1. Survey sampling: the Horvitz-Thompson estimator

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- Sampling ( $n < N$  items) without replacement: the  $R_i$ 's are dependent (but exchangeable);  $P(R_i = 1) = n/N$  for each  $i = 1, \dots, N$ ,

$$P(R_i = 1, R_j = 1) = \frac{n}{N} \left( \frac{n-1}{N-1} \right), \quad 1 \leq i, j \leq N, \quad i \neq j,$$

$$P(\underline{R} = \underline{r}) = \frac{1}{\binom{N}{n}} \quad \text{for } \underline{r} = (r_1, \dots, r_n), \quad \text{with } \sum_1^n r_i = n.$$

Note that  $\sum_1^N R_i = n$  is fixed (and non-random).

- Goal: Estimate  $T \equiv \sum_{i=1}^N y_i$  (or, equivalently,  $\mu_N \equiv N^{-1}T = N^{-1} \sum_1^N y_i$ ).
- An estimator based only on the  $y_i$ 's: the Horvitz-Thompson estimator of  $T$  is

$$\hat{T} = \sum_{i:R_i=1} \frac{1}{\pi_i} y_i = \sum_{i=1}^N \frac{R_i}{\pi_i} y_i.$$

# 1. Survey sampling: the Horvitz-Thompson estimator

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- Properties of  $\hat{T}$ :

- ▶  $E(\hat{T}) = \sum_{i=1}^N \frac{E(R_i)}{\pi_i} y_i = \sum_{i=1}^N y_i = T.$

- ▶ Bernoulli sampling (BS):

$$\begin{aligned} \text{Var}(\hat{T}_{BS}) &= \sum_{i=1}^N \frac{\text{Var}(R_i)}{\pi_i^2} y_i^2 = \sum_{i=1}^N \frac{\pi_i(1 - \pi_i)}{\pi_i^2} y_i^2 \\ &= \sum_{i=1}^N \frac{1 - \pi_i}{\pi_i} y_i^2 = \frac{1 - n/N}{n/N} \sum_{i=1}^N y_i^2 \\ &= \frac{N - n}{n} \sum_{i=1}^N y_i^2 = n \frac{N - 1}{n} \left(1 - \frac{n - 1}{N - 1}\right) \frac{1}{N} \sum_{i=1}^N y_i^2. \end{aligned}$$

- ▶ Sampling Without Replacement (SWOR):

$$\text{Var}(\hat{T}_{SWOR}) = n \frac{N^2}{n^2} \left(1 - \frac{n - 1}{N - 1}\right) \frac{1}{N} \sum_{i=1}^N (y_i - \bar{y}_N)^2.$$

# 1. Survey sampling: the Horvitz-Thompson estimator

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**Something left out:** Sampling  $n$  from  $N$  **with** replacement?

In this case  $\underline{R} = (R_1, \dots, R_N) \sim \text{Mult}_N(n, (1/N, \dots, 1/N))$ , so  $R_i \in \{0, 1, \dots, n\} \supset \{0, 1\}$ . Nonetheless, with  $\pi_i$  replaced by  $E(R_i) = n/N$ :

$$E(\hat{T}_{SWR}) = T,$$

$$\text{Var}(\hat{T}_{SWR}) = n \frac{N^2}{n^2} \frac{1}{N} \sum_{i=1}^N (y_i - \bar{y}_N)^2.$$



## 2. Adjustments of the Horvitz-Thompson estimator

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Regression: Can we use the  $x_i$ 's to help in estimating  $T$ ?

- Notation:

$X = ((1, \underline{x}_i), i \text{ s.t. } R_i = 1, 1 \leq i \leq N), n \times (p + 1) \text{ matrix};$

$Y = (y_i, i \text{ such that } R_i = 1, 1 \leq i \leq N), n \times 1 \text{ vector}$

$W = \text{diag}(1/\pi_i, i \text{ such that } R_i = 1, 1 \leq i \leq N), n \times n \text{ matrix.}$

- Inverse probability weighted estimate of (finite) population Least Squares coefficients  $\beta_N$  are

$$\hat{\beta} = (X^T W X)^{-1} X^T W Y.$$

- The regression estimator of  $T$  is:

$$\hat{T}_{reg} = \sum_{i=1}^N \frac{R_i}{\pi_i} (y_i - x_i \hat{\beta}) + \sum_{i=1}^N x_i \hat{\beta} = 0 + \sum_{i=1}^N x_i \hat{\beta}.$$

## 2. Adjustments of the Horvitz-Thompson estimator

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- Improvement? Let

$$\rho_N^2 = \text{variance explained by finite population regression,}$$
$$1 - \rho_N^2 = \frac{\sum_1^N (y_i - x_i \beta_N)^2}{\sum_1^N (y_i - \bar{y})^2}.$$

- Decomposition:

$$\begin{aligned}\hat{T}_{reg} &= \sum_{i=1}^N \frac{R_i}{\pi_i} (y_i - x_i \beta_N) + \sum_{i=1}^N x_i \beta_N + \sum_{i=1}^N x_i \left(1 - \frac{R_i}{\pi_i}\right) (\hat{\beta} - \beta_N) \\ &= \sum_{i=1}^N \frac{R_i}{\pi_i} (y_i - x_i \beta_N) + \sum_{i=1}^N x_i \beta_N + \sum_{i=1}^N x_i \left(1 - \frac{R_i}{\pi_i}\right) O_p(n^{-1/2}) \\ &\equiv I + II + O_p(N/\sqrt{n}).\end{aligned}$$

where

$$\begin{aligned}\text{Var}(I) &= (1 - \rho_N^2) \text{Var}(\hat{T}) \\ \text{Var}(II) &= 0.\end{aligned}$$

## 2. Adjustments of the Horvitz-Thompson estimator

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- **Calibration:** Note that  $\hat{\beta}$  is a linear function of the sampled  $y_i$ 's; i.e.

$$\hat{T}_{reg} = \sum_{i:R_i=1} \frac{g_i}{\pi_i} y_i = \sum_{i:R_i=1} w_i y_i$$

where  $g_i$  depends on  $x$  and  $\pi$  but not  $\underline{y}$ : explicitly

$$g_i = 1 + (T_x - \hat{T}_x)^T (X^T W X)^{-1} x_i \sim 1$$

where  $T_x = \sum_1^N x_i$ ,  $\hat{T}_x = \sum_1^N (R_i/\pi_i) x_i$ .

**Conclusion:** The same  $1 - \rho_N^2$  reduction in variance can be achieved by adjustments of the weights:

replace  $\frac{1}{\pi_i}$  by  $\frac{g_i}{\pi_i}$ .

## 2. Adjustments of the Horvitz-Thompson estimator

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Since the  $g_i$ 's do not depend on  $\underline{y}$ , they are the same if  $y_i = x_i$ , and for estimating  $T_x$  the regression estimator is exact, so the  $g_i$ 's satisfy the following **calibration equation**:

$$\sum_{i=1}^N x_i = \sum_{i:R_i=1} \frac{g_i}{\pi_i} x_i. \quad (1)$$

Alternative definition of the  $g_i$ 's: given a “loss function”  $d(a, b)$ , choose  $\underline{g} = (g_1, \dots, g_N)$  to minimize

$$\sum_{i:R_i=1} d\left(\frac{g_i}{\pi_i}, \frac{1}{\pi_i}\right)$$

subject to (1).

- $g_{reg}$  corresponding to  $\hat{T}_{reg}$  results from  $d(a, b) = (a - b)^2/b$ .
- $g_{raking}$  corresponds to  $d(a, b) = a(\log a - \log b) + (b - a)$ ; see Deville and Särndal (1992).

## 2. Adjustments of the Horvitz-Thompson estimator

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- **Estimated weights:** Robins, Rotnitzky, and Zhao (1994)
  - ▶ Fit a logistic regression model to predict  $R_i$  from  $x_i$ .
  - ▶ Write  $p_i = \hat{\pi}_i$  for the fitted probability.
  - ▶ The estimating equations for this logistic regression model can be written as

$$\sum_{i=1}^N x_i p_i = \sum_{i=1}^N x_i R_i \quad \text{or} \quad \sum_{i=1}^N x_i \hat{\pi}_i = \sum_{i=1}^N x_i R_i. \quad (2)$$

Since  $1/\pi_i$  corresponds to  $g_i/\pi_i$  in calibration, we let  $1/\hat{\pi}_i = h_i/\pi_i$  in this “estimated weights” setting, and then rewrite (2) as

$$\sum_{i=1}^N x_i \frac{\pi_i}{h_i} = \sum_{i=1}^N R_i x_i. \quad (3)$$

This is similar to the calibration equations (1), but it has the weights on the left side rather than the right side.

## 2. Adjustments of the Horvitz-Thompson estimator

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- Comparison: estimated weights versus calibration
  - ▶ Advantages: The weights  $h_i$  always exist and are non-negative.
  - ▶ Disadvantages: All the  $x_i$ 's are required, as opposed to *sampled*  $x_i$ 's and population total for calibration.

### 3. The “paradox”

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Even though  $\pi_i$  is known, adjusting the weights from  $1/\pi_i$  to  $g_i/\pi_i$  or to  $1/\hat{\pi}_i$  gives an estimator of  $T$  with **reduced variance**. Using estimated weights rather than known weights **reduces variances**.

**One resolution:** Compare the regression estimator (special case of calibration) to a decomposition of the Horvitz Thompson estimator:

$$\hat{T} = \sum_{i=1}^N \frac{R_i}{\pi_i} (y_i - x_i \beta_0) + \sum_{i=1}^N \frac{R_i}{\pi_i} x_i \beta_0 \quad (4)$$

while

$$\begin{aligned} \hat{T}_{reg} = & \sum_{i=1}^N \frac{R_i}{\pi_i} (y_i - x_i \beta_0) + \sum_{i=1}^N x_i \beta_0 \\ & + \sum_{i=1}^N x_i \left( 1 - \frac{R_i}{\pi_i} \right) (\hat{\beta} - \beta_0). \end{aligned} \quad (5)$$

### 3. The “paradox”

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- The first terms in the last two displays are the same.
- The second term in (5) involves the known population total  $\sum_1^N x_i$  of the  $x_i$ 's, while the second term in (4) involves the **estimated total**.
- The third term (smaller order) term in (5) is not present in (4).

Conclusion: for large enough  $n$  and  $N$ ,  $\hat{T}_{reg}$  will always be at least as efficient as  $\hat{T}$ .

- Other resolutions: via projections of influence functions (Henmi & Eguchi 2004, RRZ 1994)
- Further examples: Lawless, Kalbfleisch, Wild (1999); Zou & Fine (2002) .



## 4. Parametric Models & Super-populations

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- Suppose that  $\mathcal{P} = \{P_\theta : \theta \in \Theta \subset \mathbb{R}^d\}$  is a parametric model.
- Suppose that for complete data  $W_i, 1 \leq i \leq N$

$$N\mathbb{P}_N\psi(W_i; \theta) = \sum_{i=1}^N U_i(\theta)$$

are unbiased estimating equation(s): typically  $\theta_N$  solving

$$\sum_{i=1}^N U_i(\theta_N) = 0$$

satisfies  $\sqrt{N}(\theta_N - \theta_0) \rightarrow_d N_d(0, \Sigma)$  where  $\Sigma = A^T B A$ .  
Replacing  $y_i$  by  $U_i(\theta)$  above yields  $\hat{\theta}_N$  satisfying

$$\sum_{i=1}^N \frac{R_i}{\pi_i} U_i(\hat{\theta}) = 0$$

where  $\sum_{i=1}^N \frac{R_i}{\pi_i} U_i(\theta)$  is the Horvitz-Thompson estimator of  $\sum_{i=1}^N U_i(\theta)$ . (Binder (1983))

## 4. Parametric Models & Super-populations

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- The above  $\hat{\theta}_N =$  Horvitz-Thompson estimator of  $\theta_N$ .
- Calibration estimators of estimating functions? Yes; see:
  - ▶ Rao, Yung, and Hidiroglou (2002).
  - ▶ Särndal, Swenson, and Wretman (2003).
- Rewrite of regression estimator:

$$\hat{T}_{reg} = \sum_{i=1}^N \frac{R_i}{\pi_i} (y_i - x_i \hat{\beta}) + \sum_{i=1}^N x_i \hat{\beta} = \sum_{i=1}^N \left\{ \frac{R_i}{\pi_i} y_i + \left( 1 - \frac{R_i}{\pi_i} \right) x_i \hat{\beta} \right\}$$

Replacing  $y_i$  (real-valued) by  $U_i(\theta)$  (vector) yields

$$T_N(\theta) = \sum_{i=1}^N \left\{ \frac{R_i}{\pi_i} U_i(\theta) + \left( 1 - \frac{R_i}{\pi_i} \right) \phi_i \right\}$$

where  $\phi_i$  is a  $d$ -vector of arbitrary functions of the data that are available for all  $N$  observations.

## 4. Parametric Models & Super-populations

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- Solutions  $\hat{\theta}_N$  of  $T_N(\hat{\theta}_N) = 0$  gives the class of Augmented Inverse Probability Weighted Estimators (AIPW estimators) of Robins, Rotnitzky, and Zhao (1994).
- Superpopulation setting:  $\{(x_i, y_i) : 1 \leq i \leq N\}$  is the realization of a random sample from a population or (hypothetical) super-population. Thus in the simple context of estimating a total or mean, we suppose that  $Y_1, \dots, Y_N$  are i.i.d.  $P$  on  $\mathbb{R}$  with  $\mu = E(Y_1)$  and  $\sigma_Y^2 = \text{Var}(Y_1) < \infty$ .
- We want to study the Horvitz-Thompson estimator  $\hat{\mu} = N^{-1}\hat{T}$  as an estimator of  $\mu = E(Y_1)$ .

## 5. Limit theory, part 1

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- Key decomposition: Note that:

$$\begin{aligned}\sqrt{N}(\hat{\mu} - \mu) &= \sqrt{N}(\mu_N - \mu) + \sqrt{N}(\hat{\mu}_N - \mu_N) \\ &= \sqrt{N}(\bar{Y}_N - \mu) + \frac{1}{\sqrt{N}} \sum_{i=1}^N \left( \frac{R_i}{\pi_i} - 1 \right) Y_i \\ &= \sqrt{N}(\bar{Y}_N - \mu) + \frac{N}{n} \frac{1}{\sqrt{N}} \sum_{i=1}^N (R_i - \pi_i) Y_i \\ &= I_N + II_N\end{aligned}$$

where  $\mu_N = N^{-1} \sum_{i=1}^N Y_i = N^{-1}T$ .

## 5. Limit theory, part 1

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- $I_N = \sqrt{N}(\bar{Y}_N - \mu) \rightarrow_d \sigma Z_1$  where  $Z_1 \sim N(0, 1)$ .
- In the three cases *BS*, *SWOR*, and *SWR*, the second term  $II_N$  can be rewritten as

$$II_N = \sqrt{\frac{N}{n}} \sqrt{n} \left( \frac{1}{n} \sum_{i=1}^N R_i Y_i - \bar{Y}_N \right).$$

- Assuming  $n/N \rightarrow \lambda \in (0, 1)$ ,

$$II_N \rightarrow_d \begin{cases} \sqrt{\frac{1-\lambda}{\lambda}} \sqrt{E(Y^2)} Z_2, & \text{for } BS, \\ \sqrt{\frac{1-\lambda}{\lambda}} \sigma Z_2, & \text{for } SWOR, \\ \sqrt{\frac{1}{\lambda}} \sigma Z_2, & \text{for } SWR \end{cases}$$

where  $Z_2 \sim N(0, 1)$  is independent of  $Z_1$ .

## 5. Limit theory, part 1

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- Putting the results for  $I_N$  and  $II_N$  together yields:

$$\sqrt{n}(\hat{\mu}_N - \mu) \rightarrow_d \begin{cases} N(0, \lambda\sigma^2 + (1 - \lambda)E(Y^2)), & \text{for } BS, \\ N(0, \sigma^2), & \text{for } SWOR, \\ N(0, (\lambda + 1)\sigma^2), & \text{for } SWR. \end{cases}$$

- If  $E(Y) \neq 0$ , then SWOR wins!

## 6. Semiparametric Models & Super-populations

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- **Setting:**

- ▶ Semiparametric model,  $X \sim P_{\theta, \eta} \in \mathcal{P}$

- parametric part:  $\theta \in \Theta \subset \mathbb{R}^d$

- nonparametric part:  $\eta \in H \subset \mathcal{B}$ , a Banach space

- **Assumptions:** To guarantee  $\sqrt{N}$ -consistency, suppose there exist asymptotically Gaussian ML estimators  $(\hat{\theta}_n, \hat{\eta}_n)$  of  $\theta$  and  $\eta$  under i.i.d. random sampling (i.e. complete data).

- ▶ **1.** Scores  $\dot{l}_\theta$  and  $\dot{l}_\eta h = B_{\theta, \eta} h$ ,  $h \in \mathcal{H} \subset \mathcal{B}$  in a Donsker class  $\mathcal{F}$ .

- ▶ **2.** Scores  $L_2(P_0)$ -continuous at  $\theta_0, \eta_0$ .

- ▶ **3.** Information operator  $\dot{l}_\eta^T \dot{l}_\eta = B_0^* B_0$  continuously invertible on its range.

- ▶ **4.**  $(\hat{\theta}_N, \hat{\eta}_N)$  are consistent for  $(\theta_0, \eta_0)$ .

## 6. Semiparametric Models & Super-populations

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- Missing data – by design!  $X$  not observed for all items / individuals
- $\tilde{X} = \tilde{X}(X)$  observable part of  $X$  in phase 1
- **Auxiliary**  $U$  helps predict inclusion in subsample
  - ▷  $W = (X, U) \in \mathcal{W}$  observable only in validation (phase 2) sample
  - ▷  $V = (\tilde{X}, U) \in \mathcal{V}$  observable in phase 1 (for all)
- **Phase 1:**  $\{W_1, \dots, W_N\}$  i.i.d.  $P = P_W$ 
  - ▷ but observe **only**  $\{V_1, \dots, V_N\}$
- **Phase 2:** Sampling indicators  $\{R_1, \dots, R_N\}$ 
  - ▷ observe  $W_i$  (all of  $X_i$ ) if  $R_i = 1$



## 6. Semiparametric Models & Super-populations

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Many choices for the (phase 2) sampling indicators  $R_i$ ; here:

- **Bernoulli** sampling

$$Pr(R_i = 1|W_i) = Pr(R_i = 1|V_i) = \pi_0(V_i)$$

conditionally independent given the  $V_i$ 's.

- **Finite population stratified sampling**

- ▶ Partition  $\mathcal{V}$  into  $J$  strata  $\mathcal{V} = \mathcal{V}_1 \cup \dots \cup \mathcal{V}_J$ .

- ▶ Phase 1: Observe  $N_j = \sum_{i=1}^N \mathbf{1}\{V_i \in \mathcal{V}_j\}$  subjects in stratum  $j$

- ▶ Phase 2: Sample  $n_j$  of  $N_j$  **without replacement**:

- ▶ Result: sampling indicators  $R_{j,i}$  for subject  $i$  in stratum  $j$

- ▶  $(R_{j,1}, \dots, R_{j,N_j})$  exchangeable with

$$Pr(R_{ji} = 1|V_1, \dots, V_N) = n_j/N_j.$$

- ▶ The vectors  $(R_{j,1}, \dots, R_{j,N_j})$ ,  $j = 1, \dots, J$  are independent.

## 6. Semiparametric Models & Super-populations

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- Define **inverse probability weighted** (IPW) empirical measure:

$$\mathbb{P}_N^\pi = \frac{1}{N} \sum_{i=1}^N \frac{R_i}{\pi_i} \delta_{X_i}, \quad \delta_x = \text{Dirac measure at } x$$

$$\pi_i = \begin{cases} \pi_0(V_i) & \text{if Bernoulli sampling} \\ \frac{n_j}{N_j} \mathbf{1}\{V_i \in \mathcal{V}_j\} & \text{if finite pop'n stratified sampling} \end{cases}$$

- Jointly solve the finite - (for  $\theta$ ) and infinite (for  $\eta$ ) dimensional equations

$$\begin{aligned} \mathbb{P}_N^\pi \dot{l}_\theta &= 0 & \text{in } \mathbb{R}^d \\ \mathbb{P}_N^\pi \dot{l}_\eta &= 0 & \text{for all } h \in \mathcal{H}. \end{aligned}$$

- MLE for **complete data** solves same equations with  $\mathbb{P}_N$  instead of  $\mathbb{P}_N^\pi$ .

## 7. Limit theory, part 2

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- Result 1:  $\hat{\theta}_N$  solving the IPW estimating equations is asymptotically linear in that:

$$\sqrt{N}(\hat{\theta}_N - \theta_0) = \frac{1}{\sqrt{N}} \sum_{i=1}^N \frac{R_i}{\pi_i} \tilde{l}_{\theta_0}(X_i) + o_p(1) = \mathbb{G}_N^{\pi}(\tilde{l}_{\theta_0}) + o_p(1)$$

$\tilde{l}_{\theta}(x)$  is the semiparametric efficient influence function for  $\theta$  (complete data)

$$\mathbb{G}_N^{\pi} = \sqrt{N}(\mathbb{P}_N^{\pi} - P_0).$$

- Notation:
  - ▶ **Finite sampling** empirical measure for stratum  $j \in \{1, \dots, J\}$ :

$$\mathbb{P}_{j,N_j}^R = \frac{1}{N_j} \sum_{i=1}^{N_j} R_{ji} \delta_{X_{ji}}$$

- ▶ **Finite sampling** empirical process

$$\mathbb{G}_{j,N_j}^R = \sqrt{N_j} \left( \mathbb{P}_{j,N_j}^R - \frac{n_j}{N_j} \mathbb{P}_{j,N_j} \right),$$

## 7. Limit theory, part 2

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- More notation:  $\nu_j \equiv P_0(\mathcal{V}_j)$ , for  $j \in \{1, \dots, J\}$ .
- Assume:  $n_j/N_j \rightarrow_p \lambda_j \in (0, 1)$ , for  $j \in \{1, \dots, J\}$ .
- Key decomposition:

$$\mathbb{G}_N^\pi = \mathbb{G}_N + \sum_{j=1}^J \frac{N_j}{N} \left( \frac{N_j}{n_j} \right) \mathbb{G}_{j, N_j}^R;$$

that is

$$\begin{aligned} \sqrt{N}(\mathbb{P}_N^\pi - P_0) &= \sqrt{N}(\mathbb{P}_N - P_0) \\ &\quad + \sum_{j=1}^J \frac{N_j}{N} \left( \frac{N_j}{n_j} \right) \sqrt{N_j} \left( \mathbb{P}_{j, N_j}^R - \frac{n_j}{N_j} \mathbb{P}_{j, N_j} \right). \end{aligned}$$

## 7. Limit theory, part 2

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$$\begin{aligned} \sqrt{N}(\mathbb{P}_N^\pi - P_0) &= \sqrt{N}(\mathbb{P}_N - P_0) \\ &\quad + \sum_{j=1}^J \sqrt{\frac{N_j}{N}} \left( \frac{N_j}{n_j} \right) \sqrt{N_j} \left( \mathbb{P}_{j,N_j}^R - \frac{n_j}{N_j} \mathbb{P}_{j,N_j} \right) \\ &\rightsquigarrow \mathbb{G} + \sum_{j=1}^J \sqrt{\nu_j} \sqrt{\frac{1 - \lambda_j}{\lambda_j}} \mathbb{G}_j \end{aligned}$$

where:

- $(\mathbb{G}, \mathbb{G}_1, \dots, \mathbb{G}_J)$  are all independent,  $\mathbb{G}$  is a  $P_0$ -Brownian bridge process (indexed by  $\mathcal{F}$ ),  $\mathbb{G}_j$  is a  $P_j = P_0(\cdot | \mathcal{V}_j)$ -Brownian bridge process indexed by  $\mathcal{F}$ , and

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$$(\mathbb{G}_N, \mathbb{G}_{1,N_1}^R, \dots, \mathbb{G}_{J,N_J}^R) \rightsquigarrow (\mathbb{G}, \sqrt{\lambda_1(1 - \lambda_1)}\mathbb{G}_1, \dots, \sqrt{\lambda_J(1 - \lambda_J)}\mathbb{G}_J).$$

## 7. Limit theory, part 2

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- Upshot, raw weighted likelihood (Horvitz-Thompson):

$$\sqrt{N}(\hat{\theta}_N - \theta_0) = \mathbb{G}_N^R(\tilde{\ell}_{\theta_0, \eta_0}) + o_p(1) \rightarrow_d N(0, \Sigma)$$

where  $\tilde{l}_0 \equiv \tilde{\ell}_{\theta_0, \eta_0}$  is the efficient influence function for  $\theta$  with complete data, and

$$\Sigma = \begin{cases} I_0^{-1} + \sum_{j=1}^J \nu_j \frac{1-\lambda_j}{\lambda_j} E_j(\tilde{\ell}_0^{\otimes 2}), & \text{Bernoulli sampling} \\ I_0^{-1} + \sum_{j=1}^J \nu_j \frac{1-\lambda_j}{\lambda_j} \text{Var}_j(\tilde{\ell}_0), & \text{SWOR} \\ I_0^{-1} + \sum_{j=1}^J \nu_j \frac{1}{\lambda_j} \text{Var}_j(\tilde{\ell}_0), & \text{SWR.} \end{cases}$$

- Gain from stratified sampling is **centering** of efficient scores
  - ▶ Can reduce variance via finite popl'n sampling.
  - ▶ Select strata via covariates so that  $\tilde{\ell}_0$  has small conditional variances on the strata
  - ▶ Going further: Improve via **calibration** or **estimated weights!**

## 7. Limit theory, part 2

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- Upshot: weighted likelihood with **calibration** or **estimated weights**: (and SWOR)

$$\begin{aligned}\sqrt{N}(\hat{\theta}_N - \theta_0) &\rightarrow_d Z \sim N(0, \Sigma), \\ \sqrt{N}(\hat{\theta}_{N,c} - \theta_0) &\rightarrow_d Z_c \sim N(0, \Sigma_c), \\ \sqrt{N}(\hat{\theta}_{N,e} - \theta_0) &\rightarrow_d Z_e \sim N(0, \Sigma_e),\end{aligned}$$

where

$$\begin{aligned}\Sigma &= I_0^{-1} + \sum_{j=1}^J \nu_j \frac{1 - \lambda_j}{\lambda_j} \text{Var}_j(\tilde{\ell}_0), \\ \Sigma_c &= I_0^{-1} + \sum_{j=1}^J \nu_j \frac{1 - \lambda_j}{\lambda_j} \text{Var}_j((I - Q_c)\tilde{\ell}_0), \\ \Sigma_e &= I_0^{-1} + \sum_{j=1}^J \nu_j \frac{1 - \lambda_j}{\lambda_j} \text{Var}_j((I - Q_e)\tilde{\ell}_0),\end{aligned}$$

## 7. Limit theory, part 2

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and, with  $Z = g(V)$ ,  $g$  known,

$$\begin{aligned} Q_{cf} &\equiv P_0[(\pi_0^{-1}(V) - 1)fZ^T]\{P_0(\pi_0^{-1}(V) - 1)Z^{\otimes 2}\}^{-1}Z, \\ Q_{ef} &\equiv P_0[\pi_0^{-1}(V)fZ^T]S_0^{-1}(1 - \pi_0(V))\dot{G}_e(Z^T\alpha_0)Z. \end{aligned}$$



## 8. Problems and further questions

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- Give a unified treatment of weighed likelihood estimation with calibration and estimated weights for semiparametric models as above.
- Extend to semiparametric models where there is no  $\sqrt{n}$ -consistent estimator of  $\eta$ .
- Both of the above are treated in Saegusa and W (2011).
- Extend to more complex sampling designs; e.g. cluster sampling?
  - ▶ Key issue: no general theory for “sampling empirical processes”.
- Estimators of variance; e.g. via bootstrap? (Saegusa, 2012).
- Behavior of all these estimators under model miss-specification?
- Incorporate model selection methods for choosing covariates in calibration and estimated weights improvements.

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