

Lecture 10

Parametric density est
- gradient ascent

Q1 on Tue 2/11
HW3 due Fri 2/7
at 11:59 pm

LV nonparametric
density
LIII supplement
uniform

HW IV + b. posted

Lecture Notes IV – Continuous distributions. Parametric density estimation.

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CDF and PDF. Sampling ✓

Examples of continuous distributions ✓

ML estimation for continuous distributions ✓

ML estimation by gradient ascent ←

when no analytic
solution exists

Reading: Ch.5, 6

Examples of continuous distributions

$$\mathcal{F}_1 = \{u_{[a,b]}, a < b\}$$

uniform

(5)

$$f(x; a, b) = \begin{cases} \frac{1}{b-a}, & x \in [a, b] \\ 0, & \text{otherwise} \end{cases}$$

(6)

$$\mathcal{F}_2 = \{N(\cdot; \mu, \sigma^2)\}$$

normal

(7)

$$f(x; \mu, \sigma^2) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

(8)

CDF

$$F(x; a, b) = \frac{1}{1 + e^{-ax-b}}, a > 0$$

(9)

logistic

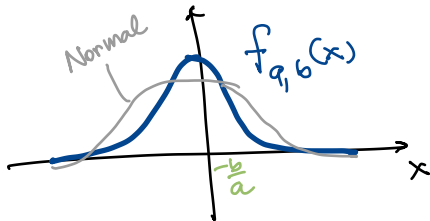
$$f(x; a, b) = \frac{ae^{-ax-b}}{(1 + e^{-ax-b})^2}$$

(10)

$$ax+b = a \left(x - \frac{-b}{a}\right) = z$$

like $\frac{1}{\sigma^2}$

mean



$$b=0$$

$$a=1$$

$$F = \frac{1}{1 + e^{-x}}$$

$$f = \frac{e^{-x}}{(1 + e^{-x})^2}$$

Ex: symmetric $f(x) = f(-x)$
arg max $f(x) = 0$

Logistic density

$$\mathcal{D} = \{x^1, \dots, x^n\} \subset (-\infty, \infty) \text{ data}$$

$$\mathcal{F} = \{f(x | \underline{a}, \underline{b}), \underline{a} > 0, \underline{b}\} \text{ model class}$$

$$1. \text{ Likelihood } L = \prod_{i=1}^n f(x_i | \underline{a}, \underline{b}) \text{ params}$$

$$\text{Want: } a^{ML}, b^{ML} = ?$$

$$1. l(a, b) = n \ln a - a \sum_{i=1}^n x_i - nb - 2 \sum_{i=1}^n \ln(1 + e^{-ax_i - b})$$

STAT

CALC

$$\frac{\partial l}{\partial a} = \frac{n}{a} - \sum_{i=1}^n x_i \frac{1 - e^{-ax_i - b}}{1 + e^{-ax_i - b}} = 0$$

$$\frac{\partial l}{\partial b} = - \sum_{i=1}^n \frac{1 - e^{-ax_i - b}}{1 + e^{-ax_i - b}} = 0$$

solve for $\underline{a}, \underline{b}$

NUMERICALLY

by Gradient Ascent

ML estimation by gradient ascent

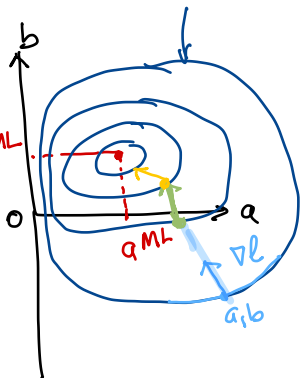
level curves
 $l(a,b) = \text{constant}$

$$l(a,b) \rightarrow \frac{1}{n} l(a,b)$$

$$\underline{l(a,b)} = n \ln a - a \sum_i x_i - nb - 2 \sum_{i=1}^n \ln(1 + e^{-ax_i - b})$$

$$\frac{\partial l}{\partial a} = \frac{n}{a} - \sum_{i=1}^n x_i \frac{1 - e^{-ax_i - b}}{1 + e^{-ax_i - b}} = 0$$

$$\frac{\partial l}{\partial b} = - \sum_{i=1}^n \frac{1 - e^{-ax_i - b}}{1 + e^{-ax_i - b}} = 0$$

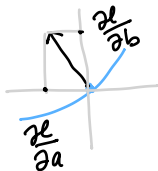


for any $a, b \rightarrow l(a,b)$

initial $(a^0, b^0) : \nabla l(a^0, b^0) = \begin{bmatrix} \frac{\partial l}{\partial a} \\ \frac{\partial l}{\partial b} \end{bmatrix} \neq 0$

$(a^1, b^1) : \nabla l(a^1, b^1) \neq 0$

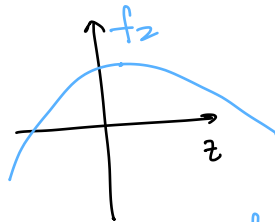
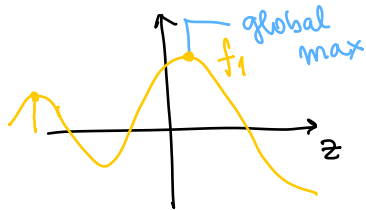
$(a^2, b^2) : \nabla l(a^2, b^2) \neq 0 \dots$



logistic density estimation

$$\nabla l(a, b) = \begin{bmatrix} \frac{\partial l}{\partial a} \\ \frac{\partial l}{\partial b} \end{bmatrix} \in \mathbb{R}^2$$

$$\nabla^2 l(a, b) = \begin{bmatrix} \frac{\partial^2 l}{\partial a^2} & \frac{\partial^2 l}{\partial a \partial b} \\ \frac{\partial^2 l}{\partial a \partial b} & \frac{\partial^2 l}{\partial b^2} \end{bmatrix} \in \mathbb{R}^{2 \times 2} \text{ symmetric}$$



$$f_1' = 0$$

$$f_1'' < 0$$

f_1 has 2 local maxima

f_2 has 1 local max
= global max

$$f_2' = 0$$

$$\left[f_2'' < 0 \text{ for all } z \right] \Rightarrow \text{at most 1 maximum}$$

• if $\nabla^2 l(a, b) < 0$ for all a, b
 $\Rightarrow l$ has at most 1 maximum

• $A < 0$ if $\lambda_1, \lambda_2 < 0$

Gradient Ascent Algorithm

1. Initialize with some $a^0, b^0, a^0 > 0$

2. For $t=1, 2, \dots, T$

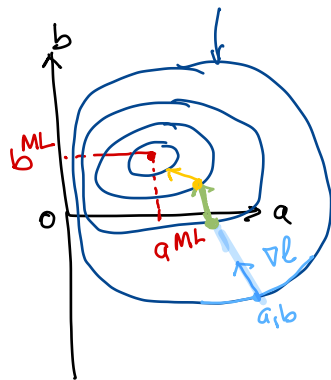
compute $\nabla \ell(a^{t-1}, b^{t-1}) = g^t \in \mathbb{R}^2$
gradient

update $a^t \leftarrow a^{t-1} + \eta \cdot \frac{\partial}{\partial a}(a^{t-1}, b^{t-1})$

$b^t \leftarrow b^{t-1} + \eta \cdot \frac{\partial}{\partial b}(a^{t-1}, b^{t-1})$

If $\|g^t\| < \text{tol}$ STOP and output a^t, b^t

$$\begin{bmatrix} a^t \\ b^t \end{bmatrix} \leftarrow \begin{bmatrix} a^{t-1} \\ b^{t-1} \end{bmatrix} + \eta g^t$$



Details

- init $a^0, b^0 \leftarrow$ random (or best of knowledge)

Alg always converges to a^{ML}, b^{ML}

- T number of steps

Safety against ∞ loops

correctly run should exit **with convergence**

- CONVERGENCE TEST

Rule 1 $\|g^t\| \leq \text{tol} ?$
NOT RELIABLE

$$\|z_1, z_2\| = \sqrt{z_1^2 + z_2^2}$$

Rule 2

rel change $\leq \text{tol}$

$$0 < \left| \frac{\ell(a^t, b^t) - \ell(a^{t-1}, b^{t-1})}{\ell(a^{t-1}, b^{t-1})} \right| < \underline{\underline{\epsilon}}$$

use other
diagnoses

$$\text{tol} > \sqrt{\epsilon_{\text{machine}}}$$

$$\epsilon = 10^{-3, 4, 6}$$

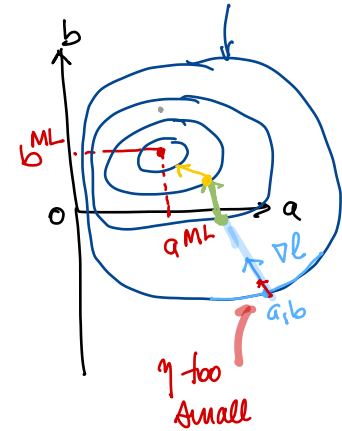
- choice of step size $\eta > 0$
usually $\eta \ll 1$

i) η small

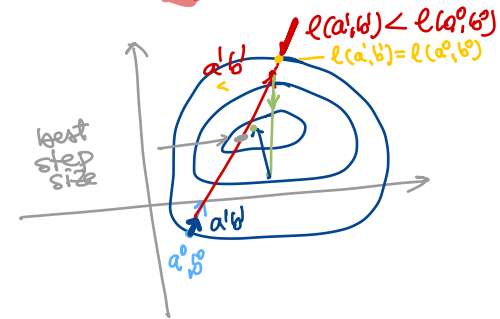
$\nabla \ell(a', b') \propto \nabla \ell(a^*, b^*)$
advance too slow!

ii) η too large

instability
increase of ℓ too slow
OR divergence
 $\ell \uparrow \downarrow$



η too large:



Why ∇ ascent not optimal

approx
gradient direction

$$g^t = \nabla f(\tilde{x}^t)$$

Example

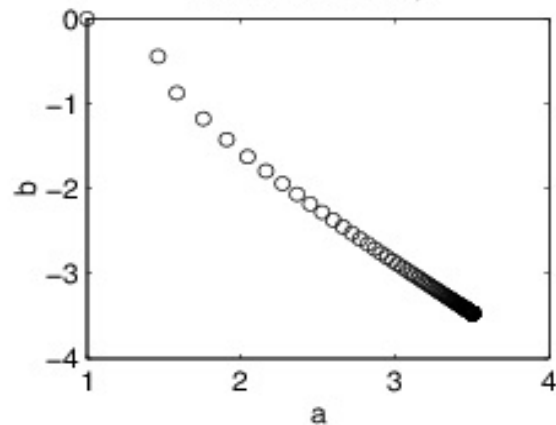
approximate
direction to
optimum
from •

Newton ✓
LBFGS (quasi-Newton) ✓
Heavy Ball ✓

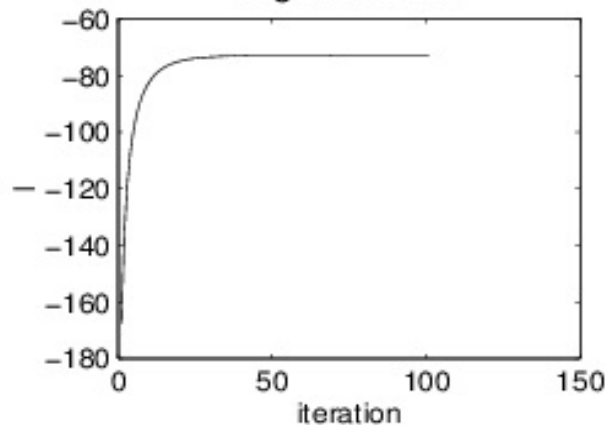
LBFGS optimization
routine

ML estimation for continuous distributions

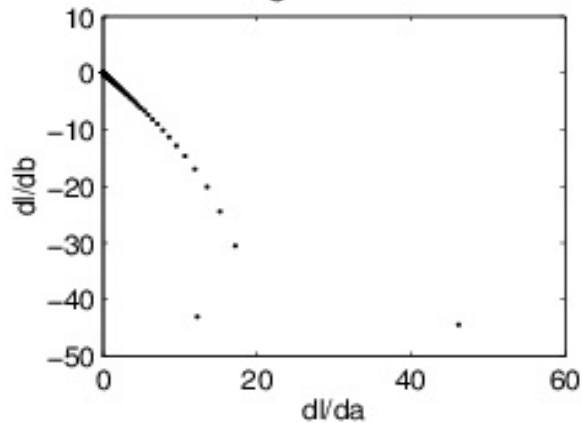
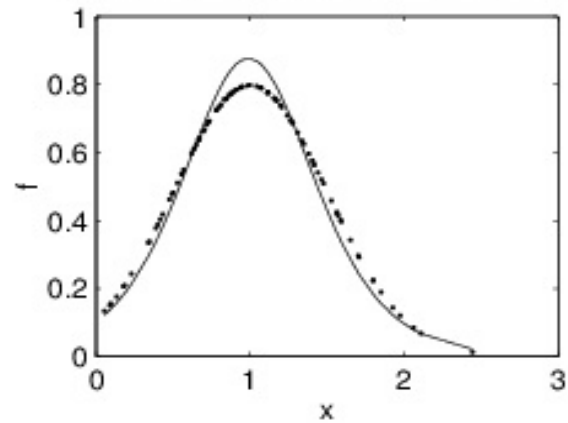
Parameters a,b



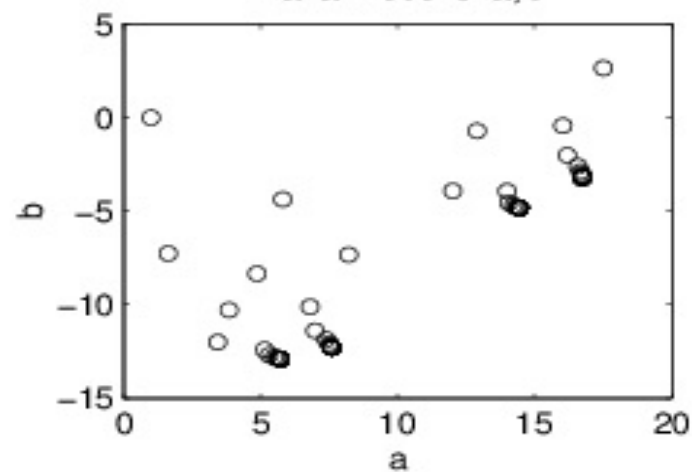
Log-likelihood



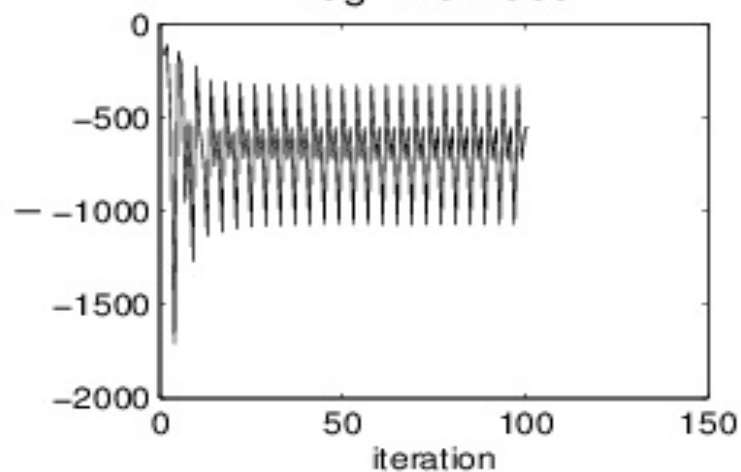
gradient

Estimated f $a=3.5078$ $b=-3.4715$ 

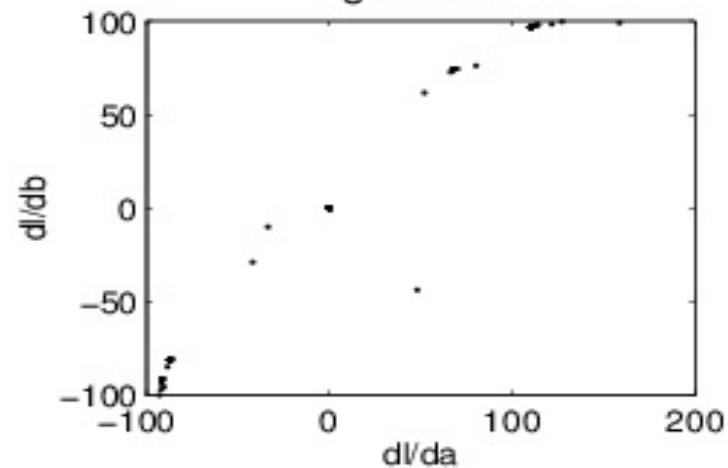
Parameters a,b



Log-likelihood



gradient

Estimated f $a=16.7453$ $b=-3.1889$ 