

Lecture 15

Imputation

HW5 - TB Posted
Project TB Posted

Lecture Notes VII – Missing Data and Imputation

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The missing data problem

MCAR ✓
MAR ✓
MNAR ?X

Imputation for MAR

$$p(y | x, R=1)$$

Imputation for monotone missingness (MAR)



What is the distribution of R ?

- ▶ Let data $\mathcal{D} = \{(x^1, y^1), \dots (x^n, y^n)\} \cup \{x_{n+1}, \dots x_{n+m}\}$
 - ▶ **complete data** $\{(x^1, y^1), \dots (x^n, y^n)\}$ with $R^{1:n} = 1$
 - ▶ **data with missing values** $\{x_{n+1}, \dots x_{n+m}\}$ with $R^{n+1:n+m} = 0$

MCAR Missing Completely At Random $R \perp (X, Y)$

- ▶ no bias if only observed Y values $\{y^1, \dots y^n\}$ used
- ▶ Can also use imputation as in MAR case

MAR Missing At Random $R \perp Y \mid X$

- ▶ **bias possible** if only observed Y values $\{y^1, \dots y^n\}$ are used because $R \not\perp Y$
- ▶ $\{(x^1, y^1, R^1), \dots (x^n, y^n, R^n)\}$ together with $\{(x^{n+1}, R^{n+1}), \dots (x^{n+m}, R^{n+m})\}$ has information about $\{y^{n+1}, \dots y^{n+m}\}$
- ▶ Probability distribution of missing values $Y^{n+1:n+m}$ is

$$Y \sim p(Y \mid X, R = 0) \quad \text{and} \quad \boxed{p(Y \mid X, R = 0) = p(Y \mid X, R = 1)} \quad (1)$$

Imputation for MAR with Monothone Missing data

- ▶ **Example** Clinical trials with drop-out Each patient i is observed for a $t = 1, 2, \dots, T^i$ with $T^i \leq p$. Hence $y^i = (y_1^i, \dots, y_{T^i}^i)$.
- ▶ T can depend on the previous values $y^{1:T}$ but not on the future values $y^{T+1:p}$.
- ▶ T^i is the **missingness variable**
- ▶ $x_{1:t}^i$ is the "always observed" data
- ▶ $x_{t+1:p}^i$ is the **missing** data

Setting ("clinical trial") longitudinal variables $x \in \mathbb{R}^p$

data $x_1^i \dots x_t^i \mid y_{t+1}^i \dots y_p^i$

missingness $R_1^i \dots R_t^i \mid R_{t+1}^i \dots R_p^i \Rightarrow t^i$

Handwritten notes: "dropped" above $y_{t+1}^i \dots y_p^i$, "missing" above $R_{t+1}^i \dots R_p^i$, and a bracket under $R_{t+1}^i \dots R_p^i$ with "=0" below it.

MAR $Y \perp R \mid X$

$x_{t+1:p} \equiv \underline{y_{t+1:p}} \perp t \mid x_{1:t}$

$p(y \mid x, R=1)$ for obs data

$t = 1, 2, 3, \dots, p-1$ levels of missingness

Imputation for MAR with Monothone Missing data

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- ▶ T can depend on the previous values $y^{1:T}$ but not on the future values $y^{T=1:p}$.
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- ▶ $x_{t+1:p}^i$ is the **missing data**

$T = \text{stopping time}$

for $t = 1, 2, \dots, p-1$
 want: estimate $p(x_{t+1} | x_{1:t}, T=t) = p(\underbrace{x_{t+1}}_{\text{obs}} | x_{1:t}, \underbrace{T=t}_{\text{obs}})$
 ↑ missing
 want

Alg 1

$i=1$ 0 $\rightarrow t^1=1$
 $i=2$ 0 1 0 $t^2=3$
 $i=3$ 1 $t^3=4$
 $\cdot$ 0 1 1 1 0 0 $t^4=6$
 $\cdot$ 0 0 1 1 0 $t^5=5$
 $\cdot$ 0 1 x_3^6 $t^6=2$
 x_1^6, x_2^6 missing

$$p(x_3^6 | x_1^6, x_2^6, T=2) = \left(\frac{1}{2}, \frac{1}{2}\right)$$

$$p(x_2 | x_1, T=1) = \begin{cases} x_1=1 & ? \\ x_1=0 & \left(\frac{3}{4}, \frac{1}{4}\right) \end{cases}$$

$$P(X_4 | X_{1:3}, T=3) = ? \text{ no data !!}$$

0 1 0
no data either

Need additional assumptions

Ex. 1 $X_{t+1} \mid \{X_j = 0, j=1:t\}$

Ex. 2. $X_{t+1} \mid X_t$

Ex. 3. $X_{t+1} \mid X_t$ same way for all t

$$P(X_{t+1} | X_t) \equiv P(X_{t+1} | X_t, T) = \begin{pmatrix} \frac{4}{6} & \frac{2}{6} \\ 1 & 0 \end{pmatrix}$$

0
0 1 0 X_4^2
1

0 1 1 0 0

0 0 1 1 0

0 1

use this Ex1

Back to original question

θ = param of interest

Eg

$$\theta = E[X_t]$$

$$\theta = P[\text{longest sequence of 1's}]$$

...

Need $P[X] \equiv P[X_{1:p}]$

$$X = X_{1:t} \mid \underbrace{X_{t+1:p}}_{\text{missing}}$$

can be imputed

$$P(X) = \underbrace{P(X_{1:t})}_{\text{known}} \underbrace{P(X_{t+1} | X_{1:t})}_{\text{known}} \underbrace{P(X_{t+2} | X_{t+1}, X_{1:t})}_{\text{known}} \cdots \underbrace{P(X_p | X_{1:p-1})}_{\text{known}}$$

(chain rule)

known $\leftarrow$ Alg 1

Need $P[X] \equiv P[X_{1:p}]$

$$X = X_{1:t} \mid \underbrace{X_{t+1:p}}_{\text{missing}}$$

$$P(X) = P(X_{1:t})P(X_{t+1}|X_{1:t})P(X_{t+2}|X_{t+1}, X_{1:t}) \cdots P(X_p|X_{1:p-1})$$

Moreover T also has info about $X_{1:T}$, therefore

$$P(X) = \sum_{t=1}^p p(X, t) =$$

$$= \sum_{t=1}^p P(T=t)P(X|T=t)$$

$$= \sum_{t=1}^p \underbrace{P(T=t)}_{\text{from data}} \underbrace{P(X_{1:t}|T=t)}_{\text{from data: sequences of length } t} \underbrace{P(X_{t+1:p}|X_{1:t})}_{\text{by Alg 1}}$$

$$\begin{array}{l} T=1 \mid 0 \\ \quad 0 \ 1 \ 0 \\ \mid 1 \\ \quad 0 \ 1 \ 1 \ 1 \ 0 \ 0 \\ \quad 0 \ 0 \ 1 \ 1 \ 0 \\ \parallel 0 \ 1 \end{array}$$

$$P(T): \begin{array}{c} T \quad 1 \quad 2 \quad 3 \quad 4 \quad 5 \quad 6 \\ \frac{2}{6} \quad \frac{1}{6} \quad \frac{1}{6} \quad \frac{1}{6} \quad \frac{1}{6} \end{array}$$

$$P(X_1|T=1) \quad \begin{array}{c} 0 \quad 1 \\ \frac{1}{2} \quad \frac{1}{2} \end{array}$$

$$P(X_1, X_2|T=2) = \begin{cases} 1 & X_1 X_2 = 01 \\ 0 & \text{otherwise} \end{cases}$$

etc

Finally: $\rightarrow$ use $P(X)$ to estimate θ
 $\rightarrow$ use imputation $\Rightarrow$ complete sample $\Rightarrow$ estimate θ