STAT 403

5/16/25

# Lecture 18

Gibbs Sampeing



### Lecture Notes VIII - Markov Chain Monte Carlo

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### Notation

- ▶  $V = \{X_1, ..., X_n\}$  set of random variables (nodes of a graphical model) also known as Markov network
- $X_{1:n} \in \{\pm 1\}$  (for simplicity)
- $E = \{(i, j), 1 \le i < j \le n\}$  edges of graph
- graph is not complete, some edges are missing
- We write  $i \sim j$  for  $(i, j) \in E$  or  $(j, i) \in E$
- neigh<sub>i</sub> = neighbors of  $X_i$

• Markov property  $X_i \perp$  all other variables | neigh<sub>i</sub>

•  $x = (x_1, \dots, x_n) \in \{\pm 1\}^n = S$  an assignment to all variables in V

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▶  $x = (x_1, ..., x_n) \in \{\pm 1\}^n = S$  an assignment to all variables in V ▶ Distribution over S

$$P(x) = \frac{1}{Z} e^{-\phi(x)} \quad \text{with } \phi(x) = \sum_{i=1}^{n} h_i x_i + \sum_{(i,j) \in E} h_{ij} x_i x_j$$
(1)

(and  $h_{ij} > 0$  for all  $(i, j) \in E$ )  $Z = \sum_{x \in S} e^{-\phi(x)}$ Usually, intractable to compute Z

Wanted samples  $x^1, x^2, \ldots$  from *P* 



# Gibbs sampling idea

$$P(\mathbf{x}) = \frac{1}{\mathbf{Z}} e^{-\phi(\mathbf{x})} \quad \text{with } \phi(\mathbf{x}) = \sum_{i=1}^{n} h_i x_i + \sum_{(i,j) \in E} h_{ij} x_i x_j$$

We cannot sample directly from 
$$P$$
  
But we can sample each  $X_i \sim \frac{P_{X_i|X_{-i}}}{P_X} = P_{X_i|\text{neigh}}$  for any  $i = 1 : n$   
 $P_Y \times i$  all offer variables

Px; | neigh (xi)





Ergodic Markov Jain X° initial state

$$P_{\chi}^{(t)} \longrightarrow P_{\chi}^{\infty}$$
 for any  $\chi_{0}$ 



# Gibbs sampling idea

$$P(\mathbf{x}) = \frac{1}{Z} e^{-\phi(\mathbf{x})} \quad \text{with } \phi(\mathbf{x}) = \sum_{i=1}^{n} h_i x_i + \sum_{(i,j) \in E} h_{ij} x_i x_j \quad \text{are Ling}$$

▶ We cannot sample directly from P  
▶ But we can sample each 
$$X_i \sim P_{X_i|X_{-i}} = P_{X_i|\text{neigh}_i}$$
 for any  $i = 1 : n$   
▶ Why? For any  $x_{-i}$  let  
 $\pi_i^+ = Pr[X_i = +|x_{-i}] \quad \underline{\pi_i^- = Pr[X_i = -|x_{-i}]} \quad \Pi_i^+ + \overline{\pi_i^-} = 1$  (2)  
 $\pi_i^+ = \frac{P(X_i = +1, x_{-i})}{P(x_{-i})} = \frac{P(X_i = +1, x_{-i})}{P(X_i = +1, x_{-i}) + P(X_i = -1, x_{-i})}$  (3)  
 $\pi_i^- = \frac{P(X_i = -1, x_{-i})}{P(X_i = +1, x_{-i}) + P(X_i = -1, x_{-i})} \quad \text{hence}$  (4)  
 $\frac{\pi_i^+}{\pi_i^-} = \frac{P(X_i = +1, x_{-i})}{P(X_i = -1, x_{-i})} = \frac{e^{-\phi(X_i = +1, x_{-i})}}{e^{-\phi(X_i = -1, x_{-i})}} = e^{-\phi(X_i = +1, x_{-i}) + \phi(X_i = -1, x_{-i})}$  (5)  
 $= e^{-2h_i - 2\sum_{j \sim i} h_{ij}} X_j^-$  (6)  
 $1 = \pi_i^+ + \pi_i^- \quad \text{hence} \ \pi_i^+ = \frac{e^{-2h_i - 2\sum_{j \sim i} h_{ij}}}{1 + e^{-2h_i - 2\sum_{j \sim i} h_{ij}}} = \frac{e^{-h_i - \sum_{j \sim i} h_{ij}}}{e^{h_i + \sum_{j \sim i} h_{ij}} + e^{-h_i - \sum_{j \sim i} h_{ij}}}$ 

 $\blacktriangleright X_i \, | \, \mathrm{neigh}_i \sim \mathrm{Bernoulli}(\pi_i^+)$ 

# Gibbs sampling algorithm

- 1. Initialize x<sup>0</sup> with some arbitrary values
- 2. For t = 1, 2, ... we will sample sequentially  $x^t | x^{t-1}$  as follows
  - 2.1 Pick  $i \in 1$ : *n* uniformly at random
  - 2.2 Sample  $X_i^t | \operatorname{neigh}_i \sim \operatorname{Bernoulli}(\pi_i^+)$
  - 2.3 Every T steps (where T is a LARGE number), output  $x^t$
- Q Why does this work?
- A1 We are sampling from a Markov chain on S (transition probability matrix P on next page)
- A2 If we take enough steps T, the distribution converges to the stationary distribution of this chain, let's call it P. We take a sample from it  $x^T$
- A3 If we continue for another T steps, the chain has "forgotten" about  $x^T$ ; the new sample  $x^{2T}$  is independent of  $x^T$ . Etc, samples  $x^{T,2T,...NT}$  are i.i.d. from  $P^{\infty}$
- ODO To show that  $P^{\infty} = P$  the distribution we wanted to sample from.