

Lecture 19

Gibbs sampling
in practice

⇒ Don't miss
hard lecture ⇐

Lecture Notes VIII – Markov Chain Monte Carlo

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Notation ✓

Gibbs sampling ← *mixing - in practice
sampling subsets of variables*

The detailed balance

Metropolis-Hastings sampling

Notation

- ▶ $V = \{X_1, \dots, X_n\}$ set of random variables (nodes of a **graphical model**)
also known as **Markov network**
- ▶ $X_{1:n} \in \{\pm 1\}$ (for simplicity)
- ▶ $E = \{(i, j), 1 \leq i < j \leq n\}$ **edges** of graph
- ▶ graph is not complete, some edges are missing
- ▶ We write $i \sim j$ for $(i, j) \in E$ or $(j, i) \in E$
- ▶ $\text{neigh}_i = \text{neighbors of } X_i$
- ▶ **Markov property** $X_i \perp \text{all other variables} \mid \text{neigh}_i$
- ▶ $\mathbf{x} = (x_1, \dots, x_n) \in \{\pm 1\}^n = S$ an assignment to all variables in V
- ▶ Distribution over S

$$P(\mathbf{x}) = \frac{1}{Z} e^{-\phi(\mathbf{x})} \quad \text{with } \phi(\mathbf{x}) = \sum_{i=1}^n h_i x_i + \sum_{(i,j) \in E} h_{ij} x_i x_j \quad (1)$$

(and $h_{ij} > 0$ for all $(i, j) \in E$)

- ▶ $Z = \sum_{\mathbf{x} \in S} e^{-\phi(\mathbf{x})}$
- ▶ Usually, intractable to compute Z

Wanted samples $\mathbf{x}^1, \mathbf{x}^2, \dots$ from P

Gibbs sampling algorithm

$x^t = \text{state at } t \in S$

$$|S| = 2^n$$

$$x = (x_{1:n})$$

1. Initialize x^0 with some arbitrary values
2. For $t = 1, 2, \dots$ we will sample **sequentially** $x^t | x^{t-1}$ as follows
 - 2.1 Pick $i \in 1 : n$ uniformly at random
 - 2.2 Sample $X_i^t | \text{neigh}_i \sim \text{Bernoulli}(\pi_i^+)$
 - 2.3 Every T steps (where T is a LARGE number), output x^t

Q Why does this work?

A1 We are sampling from a **Markov chain** on S (transition probability matrix P on next page)

A2 If we take enough steps T , the distribution converges to the stationary distribution of this chain, let's call it P . We take a sample from it x^T

A3 If we continue for another T steps, the chain has "forgotten" about x^T ; the new sample x^{2T} is independent of x^T . Etc, samples $x^{T, 2T, \dots, NT}$ are i.i.d. from P^∞

ODO To show that $P^\infty = P$ the distribution we wanted to sample from.

M.C Ergodic $\Rightarrow x^{t+T} \sim P_x^\infty$ stationary distribution

$x^{t+T} \perp x^t$ for T large

More detail

$T_0 = \# \text{ burn-in steps (time)}$

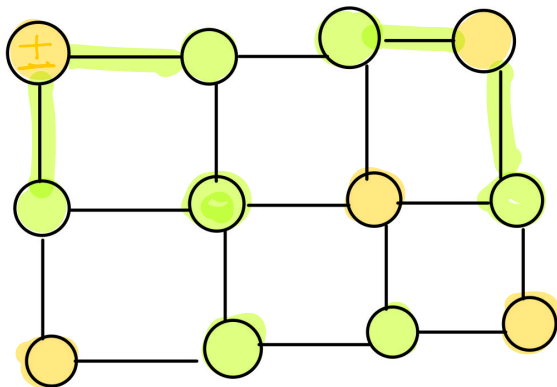
$x_0 \dots x^{T_0} = \text{first sample}$

$x_0 \rightarrow P^\infty$

$T = \# \text{ sampling steps (time)}$

$x^t \sim P^\infty$

(assumption) $\Rightarrow t > T_0$



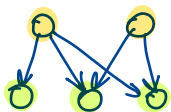
$T_0 > T$ in practice

T = mixing time

$$\lambda_2([P_{ji}]) \approx 0$$

transition matrix

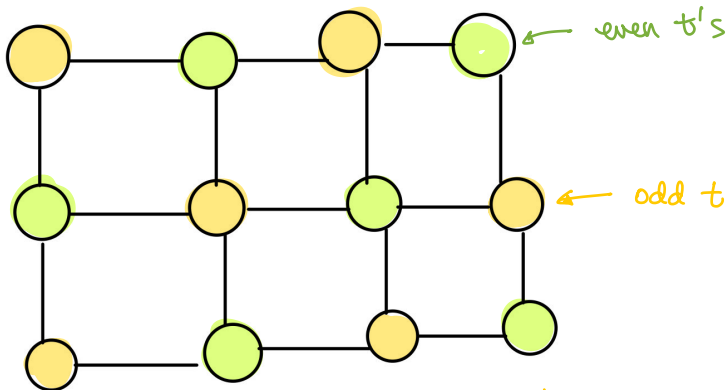
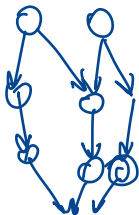
Bayes network



↓ easy ↑ hard
computationally

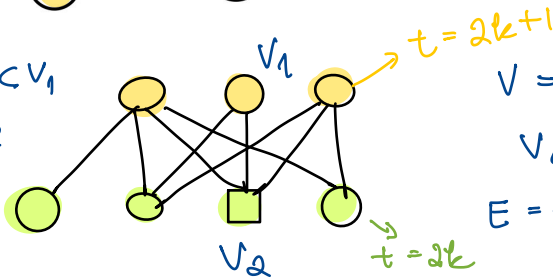
(Restricted Boltzmann Machine)

sequential
↓



$i \in V_1 \Rightarrow$
 $\text{neigh}_i \subset V_2$
 $j \in V_2 \Rightarrow \text{neigh}_j \subset V_1$

Bipartite
graph



$$V = V_1 \cup V_2$$

$$V_1 \cap V_2 = \emptyset$$

$$E = \{(i, j) \mid i \in V_1, j \in V_2\}$$