

Lecture 12

C-SVM $\rightarrow$ selecting C

Non-linear SVM

- Kernel trick
- Nonlinear SVM prediction
- RBF - effect of γ

Project

submit clustering

results alg1.txt

alg2.txt

5/23 $\leftarrow$ = 10% - 15%

Report : exam week
 $\approx$ 90% - 85%

Lecture V: Support Vector Machines and Kernel Machines

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Linear SVM's



The margin and the expected classification error

Maximum Margin Linear classifiers

Linear classifiers for non-linearly separable data

C-SVM

Non linear SVM



The “kernel trick”

Kernels

Prediction with SVM

Extensions

(L_1 SVM
Multi-class and One class SVM
SV Regression)

Reading AoNPS Ch.: Ch. 12.1–3, **HTF Ch.:** Ch 14 (14.1,14.2–14.2.4 kernels, 14.4 and equations (14.28,14.29) kernel trick, 14.5.1.–3 Support Vector Machines) 7.1–7.4, 7.7

Additional Reading: C. Burges - “A tutorial on SVM for pattern recognition”

These notes: Appendices (convex optimization) are optional.

Non-linearly separable problems and their duals

The C-SVM

$$\begin{aligned}
 &\underset{w, b, \xi}{\text{minimize}} && \frac{1}{2} \|w\|^2 + C \sum_i \xi_i \\
 &\text{s.t.} && y^i (w^T x^i + b) \geq 1 - \xi_i \\
 &&& \xi_i \geq 0 \quad \text{slack}
 \end{aligned} \tag{20}$$

regularization

In the above, ξ_i are the slack variables. Dual³.

$$\begin{aligned}
 &\underset{\alpha}{\text{maximize}} && \sum_i \alpha_i - \frac{1}{2} \sum_i \alpha_i \alpha_j y^i y^j x^i T x_j \\
 &\text{s.t.} && C \geq \alpha_i \geq 0 \text{ for all } i \\
 &&& \sum_i \alpha_i y^i = 0
 \end{aligned} \tag{21}$$

Handwritten notes: $\alpha^T \tilde{G} \alpha$, $\tilde{G}_{ij}$

⇒ two types of SV

- ▶ $\alpha_i < C$ data point x^i is "on the margin" $\Leftrightarrow y^i (w^T x^i + b) = 1$ (original SV)
- ▶ $\alpha_i = C$ data point x^i cannot be classified with margin 1 (**margin error**)
 $\Leftrightarrow y^i (w^T x^i + b) < 1$

³Lagrangean $L(w, b, \xi, \alpha, \mu) = \frac{1}{2} \|w\|^2 + C \sum_i \xi_i - \sum_i \alpha_i [y^i (w^T x^i + b) - 1 + \xi_i] - \sum_i \mu_i \xi_i$ with $\alpha_i \geq 0, \xi_i \geq 0, \mu_i \geq 0$

The margin and the expected classification error

Theorem Let $\mathcal{F} = \{\text{sgn}(w^T x), \|w\| \leq \Lambda, \|x\| \leq R\}$ and let $\rho > 0$ be any “margin”. Then for any $f \in \mathcal{F}$, w.p $1 - \delta$ over training sets

gen. error

$$\Pr[\text{err}] \equiv L_{01}(f) \leq \hat{L}_\rho + \underbrace{\sqrt{\frac{c}{n} \left(\frac{R^2 \Lambda^2}{\rho^2} \ln n^2 + \ln \frac{1}{\delta} \right)}}_{\text{r.w.s (5)}} \quad \leftarrow \text{find } f \text{ that minimizes (5)}$$

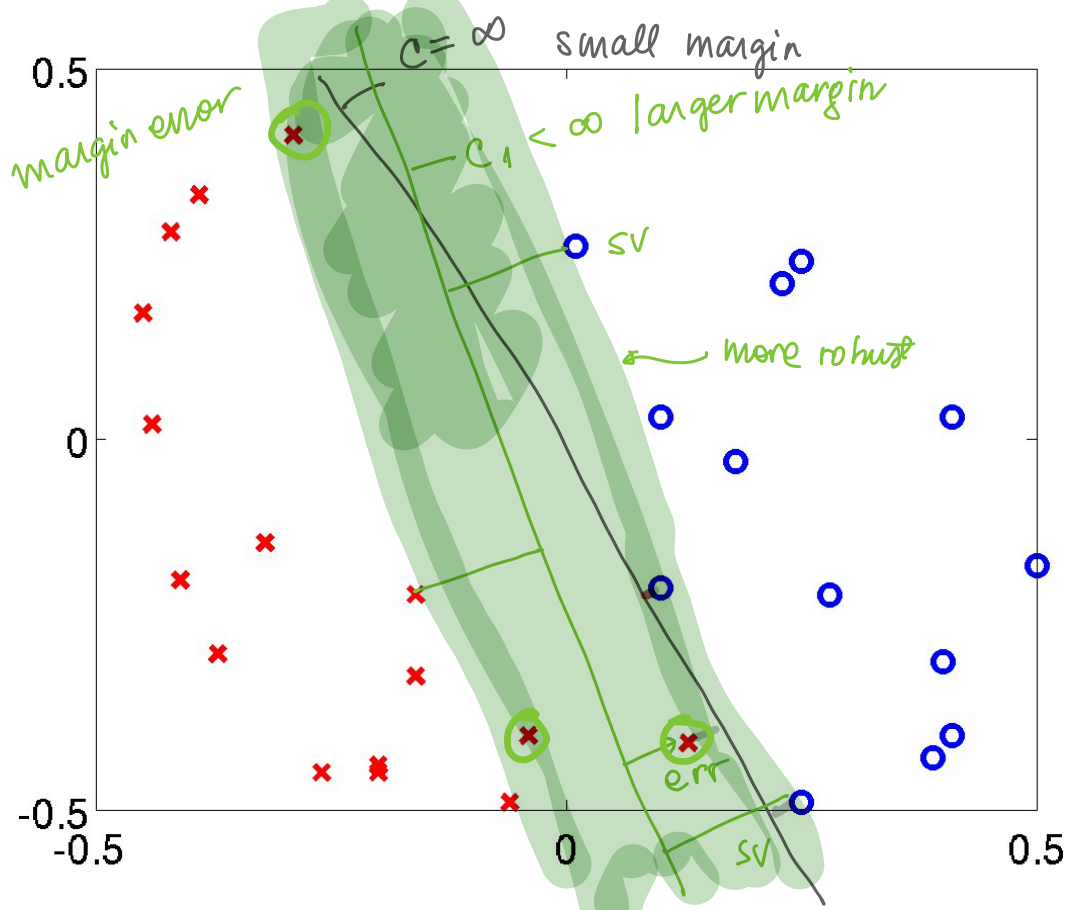
where c is a universal constant and $\hat{L}_\rho$ is the fraction of the training examples for which

$$y^i w^T x_i < \rho \quad (6)$$

- ▶ a data point i that satisfies (6) for some ρ is called a **margin error**
- ▶ For $\rho = 0$ the margin error rate $\hat{L}_\rho$ is equal to $\hat{L}_{01}$

Choosing C

- $C \uparrow \Rightarrow \sum_{i=1}^n \xi_i \rightarrow$ penalized more $\Rightarrow$ fewer margin errors (smaller)
 $\Rightarrow \|W\| \uparrow \Leftrightarrow$ margin $\downarrow$
- try $C \Rightarrow$ for all p
compute $\hat{L}_p = \frac{\# \text{ margin-errors } (p)}{n} \rightarrow \min_p \text{ r.h.s (5)} \equiv \text{Bound}(C)$
SVM(C)
 $\min_C \text{ Bound}(C)$
(for $P[\text{err}]$)
- ν -SVM $\nu = \frac{1}{C}$ (heuristic)
- Cross Validation



The ν -SVM

regularization

$$\text{minimize}_{w,b,\xi,\rho} \quad \frac{1}{2} \|w\|^2 - \nu \rho + \frac{1}{n} \sum_i \xi_i \quad (22)$$

$$\text{s.t.} \quad y^i (w^T x^i + b) \geq \rho - \xi_i \quad (23)$$

$$\xi_i \geq 0 \quad (24)$$

$$\rho \geq 0 \quad (25)$$

where $\nu \in [0, 1]$ is a parameter.

Dual⁴:

$$\text{maximize}_{\alpha} \quad -\frac{1}{2} \sum_i \alpha_i \alpha_j y^i y^j x^i T x^j \quad (26)$$

$$\text{s.t.} \quad \frac{1}{n} \geq \alpha_i \geq 0 \text{ for all } i \quad (27)$$

$$\sum_i \alpha_i y^i = 0 \quad (28)$$

$$\sum_i \alpha_i \geq \nu \quad (29)$$

$\nu \approx 10^{-1}$ n small
 $\approx 10^{-3}$ n large

Properties If $\rho > 0$ then:

- ▶ ν is an upper bound on #margin errors/ n (if $\sum_i \alpha_i = \nu$)
- ▶ ν is a lower bound on #(original support vectors + margin errors)/ n
- ▶ ν -SVM leads to the same w, b as C-SVM with $C = 1/\nu$

⁴Lagrangian $L(w, b, \xi, \rho, \alpha, \mu, \delta) = \frac{1}{2} \|w\|^2 - \nu \rho + \frac{1}{n} \sum_i \xi_i - \sum_i \alpha_i [y^i (w^T x^i + b) - \rho + \xi_i] - \sum_i \mu_i \xi_i - \delta \rho$
 with $\alpha_i \geq 0, \delta \geq 0, \mu_i \geq 0$

A simple error bound

$$L_{01}(f_n) \leq \underline{E} \left[\frac{\# \text{support vectors of } f_{n+1}}{n+1} \right] \quad (30)$$

where f_n denotes the SVM trained on a sample of size n .

Exercise Use the Homework 6 to prove this result.

Non-linear SVM

How to use linear classifier on data that is not linearly separable?

An old trick

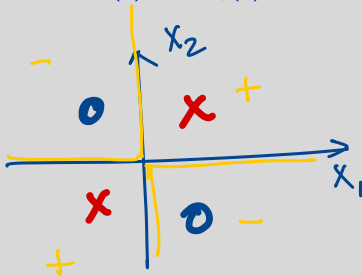
1. Map the data $x^{1:n}$ to a higher dimensional space

$$x \rightarrow z = \phi(x) \in \mathcal{H}, \text{ with } \dim \mathcal{H} \gg n.$$

2. Construct a linear classifier $w^T z + b$ for the data in $\mathcal{H}$

In other words, we are implementing the non-linear classifier

$$f(x) = w^T \phi(x) + b = w_1 \phi_1(x) + w_2 \phi_2(x) + \dots + w_m \phi_m(x) + b \quad (31)$$



$$(x_1, x_2) \rightarrow z = (x_1, x_2, x_1 x_2)$$

$$f(z) = z_3 \equiv x_1 x_2$$

↑ linear in z
↑ non-linear

Example

- ▶ Data $\{(x, y)\}$ below are not linearly separable

x		y	z		
-1	-1	1	-1	-1	1
-1	1	-1	-1	1	-1
1	-1	-1	1	-1	-1
1	1	1	1	1	1

- ▶ We map them to 3 dimensions by

$$z = \phi(x) = [x_1 \ x_2 \ x_1 x_2].$$

- ▶ Now the classes can be separated by the hypeplane $z_3 = 0$ (which happens to be the maximum margin hyperplane). Hence,
 - ▶ $w = [0 \ 0 \ 1]$ (a vector in $\mathcal{H}$)
 - ▶ $b = 0$
 - ▶ and the classification rule is $f(\phi(x)) = w^T \phi(x) + b$.
- ▶ If we write f as a function of the original x we get

$$f(x) = x_1 x_2$$

a quadratic classifier.

Non-linear SV problem

- **Primal problem** minimize $\frac{1}{2} \|w\|^2$ s.t. $y^i (w^T \underline{\phi(x^i)} + b) - 1 \geq 0$ for all i .
- **Dual problem**

$$\max_{\alpha_{1:n}} \sum_i \alpha_i - \frac{1}{2} \sum_i \alpha_i \alpha_j \underbrace{y^i y_j \phi(x^i)^T \phi(x_j)}_{\bar{G}_{ij}} \text{ s.t. } \alpha_i \geq 0 \text{ for all } i \text{ and } \sum_i y^i \alpha_i = 0 \quad (32)$$

$$G_{ij} = \boxed{\phi(x^i)^T \phi(x^j)} \text{ and } \bar{G} = \text{diag}\{y^{1:n}\}^T G \text{diag}\{y^{1:n}\}. \quad (33)$$

- $\bar{G}_{ij}$ has been redefined in terms of ϕ
- **Dual problem**

$$\max_{\alpha} 1^T \alpha - \frac{1}{2} \alpha^T \bar{G} \alpha \text{ s.t. } \alpha_i \geq 0, y^T \alpha = 0 \quad (34)$$

- Same as (19)!

$x \in \mathbb{R}^d$
 want to add all interactions $\Rightarrow \varphi(x) \equiv z \in \mathbb{R}^{d + \frac{d(d+1)}{2}}$
 d large $\Rightarrow \varphi(x)$ intractable !!

Example

$$(x_1, x_2) \mapsto (\sqrt{2}x_1, \sqrt{2}x_2, x_1^2, x_2^2, \sqrt{2}x_1x_2, 1) = z$$

↑ feature map

$$\begin{aligned} z^T z' &= \underline{2x_1x_1'} + \underline{2x_2x_2'} + \underline{2x_1x_2x_1'x_2'} + x_1^2x_1'^2 + x_2^2x_2'^2 + 1 && \sim d^2 \\ &= (1 + x_1x_1' + x_2x_2')^2 && \sim d \end{aligned}$$

kernel trick

The “Kernel Trick”

idea The result (34) is the celebrated **kernel trick** of the SVM literature. We can make the following remarks.

1. The ϕ vectors enter the SVM optimization problem only through the Gram matrix, thus only as the scalar products $\phi(x')^T \phi(x_j)$. We denote by $K(x, x')$ the function

$$K(x, x') = K(x', x) = \phi(x)^T \phi(x') \quad (35)$$

K is called the **kernel** function. If K can be computed efficiently, then the Gram matrix G can also be computed efficiently. This is exactly what one does in practice: we choose ϕ implicitly by choosing a kernel K . Hereby we also ensure that K can be computed efficiently.

2. Once G is obtained, the SVM optimization is independent of the dimension of x and of the dimension of $z = \phi(x)$. The complexity of the SVM optimization depends only on n the number of examples. This means that we can choose a very high dimensional ϕ without any penalty on the optimization cost.
3. Classifying a new point x . As we know, the SVM classification rule is

$$f(x) = w^T \phi(x) + b = \sum_{i=1}^n \alpha_i y^i \phi(x^i)^T \phi(x) = \sum_{i=1}^n \alpha_i y^i K(x^i, x) \quad (36)$$

Hence, the classification rule is expressed in terms of the support vectors and the kernel only. No operations other than scalar product are performed in the high dimensional space H .

Kernels

The previous section shows why SVMs are often called **kernel machines**. If we choose a kernel, we have all the benefits of a mapping in high dimensions, without ever carrying on any operations in that high dimensional space. The most usual kernel functions are

$$K(x, x') = (1 + x^T x')^p$$

the polynomial kernel of degree p

$$K(x, x') = \tanh(\sigma x^T x' - \beta)$$

the “neural network” kernel

$$K(x, x') = e^{-\frac{\|x - x'\|^2}{\sigma^2}}$$

the Gaussian or **radial basis function** (RBF) kernel

it's ϕ is ∞ -dimensional

↑ $\phi = ?$

(Taylor expansion)

When is $K(,)$ a kernel?

when

$\exists \phi$ such that

$$\phi(x)^T \phi(x') = K(x, x')$$

Prediction with SVM

► Estimating b

- For any i support vector, $w^T x^i + b = y^i$ because the classification is tight
- Alternatively, if there are slack variables, $w^T x^i + b = y^i(1 - \xi_i)$
- Hence, $b = y^i(1 - \xi_i) - w^T x^i$
- For non-linear SVM, where w is not known explicitly, $w = \sum_j \alpha_j y^j \phi(x_j)$. Hence,
 $b = y^i(1 - \xi_i) - \sum_{j=1}^n \alpha_j y^j K(x^i, x^j)$ for any i support vector

► Given new x

$$\hat{y}(x) = \text{sgn}(w^T x + b) = \text{sgn} \left(\sum_{i=1}^n \alpha_i y^i K(x^i, x) + b \right). \quad (38)$$

Kernel SVM Summary

- Data $\mathcal{D} = \{(x^{1:n}, y^{1:n})\}$

- Choose kernel $K \Rightarrow G = [K(x^i, x^j)]_{i,j=1:n}$

$$\tilde{G} = [y^i y^j G_{ij}]_{i,j=1:n}$$

- Choose C

- Solve (D) $\max_{\alpha} \quad 1^T \alpha - \frac{1}{2} \alpha^T \tilde{G} \alpha \quad \text{s.t.} \quad \sum_{i=1}^n \alpha_i y^i = 0$
 $0 \leq \alpha_i \leq C$
 $\uparrow$
 $n \times n$

- solution $\alpha_{1:n} \Rightarrow w = \sum_{i=1}^n \alpha_i \varphi(x^i) y^i, \quad f(x) = \sum_{i=1}^n \alpha_i y^i \varphi(x^i)^T \varphi(x) + b$

- Classify new x

$$f_{w,b}(x) = \sum_{i=1}^n \alpha_i y^i K(x^i, x) + b$$

$\downarrow$
newer represented

$\Downarrow$
compute b as before

$$\sum_{i=1}^n \alpha_i y^i K(x^i, x_{i_0}) + b = y_{i_0}$$

$i_0 = \text{s.v.}$

$\Downarrow$
solve for b

The Mercer condition

- ▶ How do we verify that a chosen K is a valid kernel, i.e. that there exists a ϕ so that $K(x, x') = \phi(x)^T \phi(x')$?
- ▶ This property is ensured by a positivity condition known as the Mercer condition.

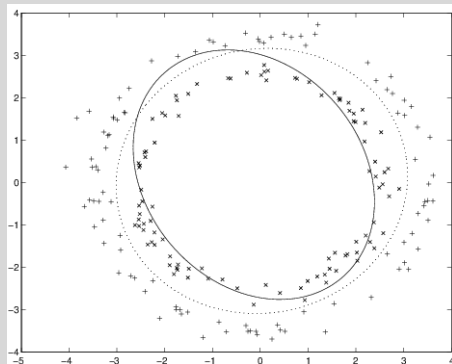
Mercer condition

Let $(\mathcal{X}, \mu)$ be a finite measure space. A symmetric function $K : \mathcal{X} \times \mathcal{X}$, can be written in the form $K(x, x') = \phi(x)^T \phi(x')$ for some $\phi : \mathcal{X} \rightarrow \mathcal{H} \subset \mathbb{R}^m$ iff

$$\int_{\mathcal{X}^2} K(x, x') g(x) g(x') d\mu(x) d\mu(x') \geq 0 \quad \text{for all } g \text{ such that } \|g(x)\|_{L_2} < \infty \quad (37)$$

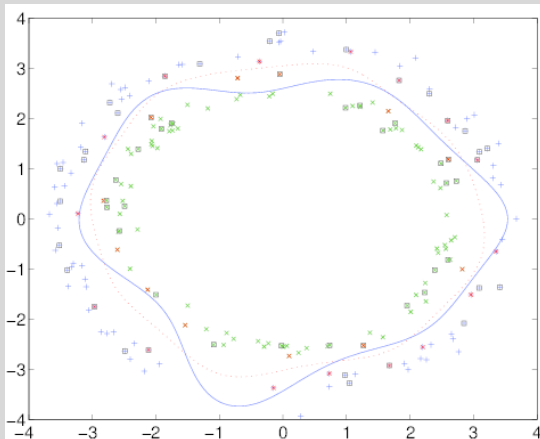
- ▶ In other words, K must be a positive semidefinite operator on L_2 .
- ▶ If K satisfies the Mercer condition, there is no guarantee that the corresponding ϕ is unique, or that it is finite-dimensional.

Quadratic kernel



- ▶ C-SVM, polynomial degree 2 kernel, $n = 200$, $C = 10000$
- ▶ The two ellipses show that a constant shift to the data ($x^i \leftarrow x^i + v$, $v \in \mathbb{R}^n$) can affect non-linear kernel classifiers.

RBF kernel and Support Vectors

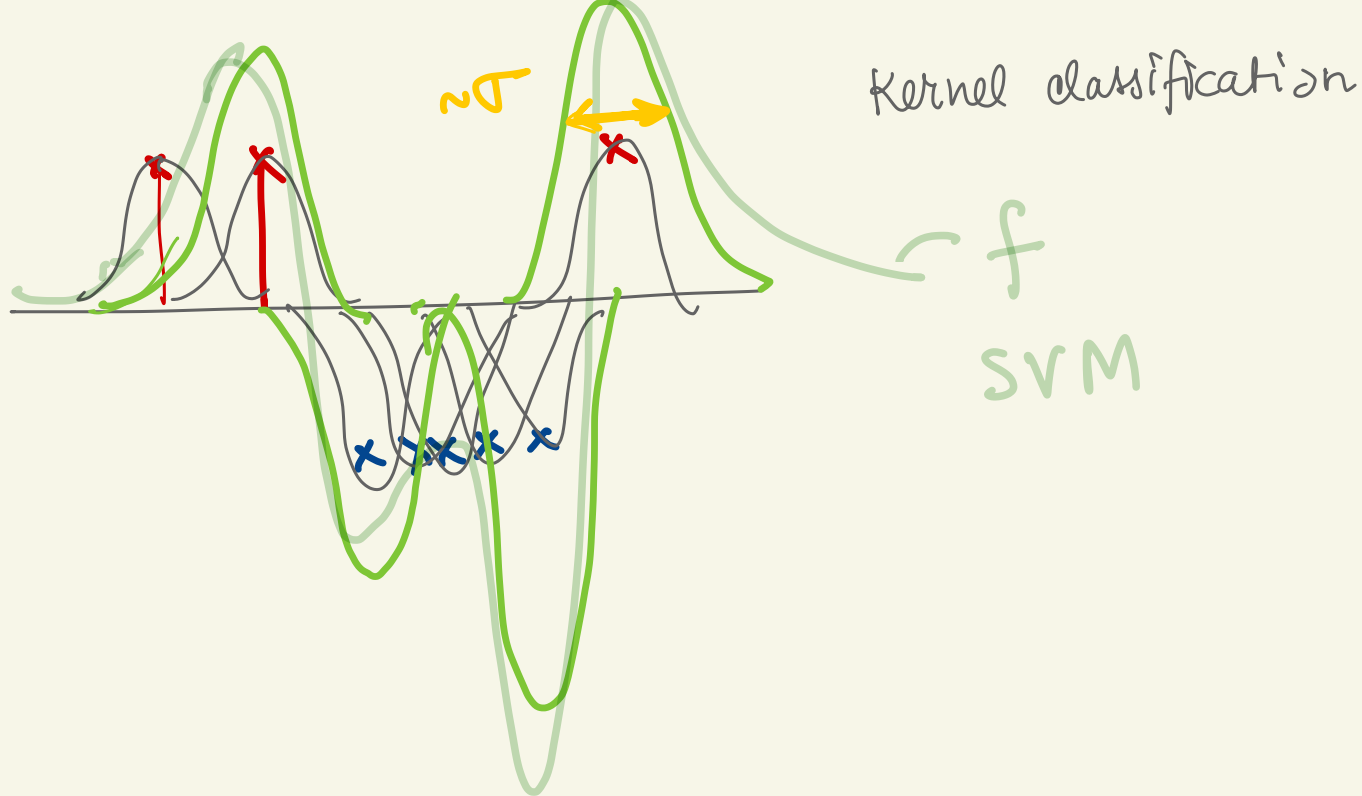


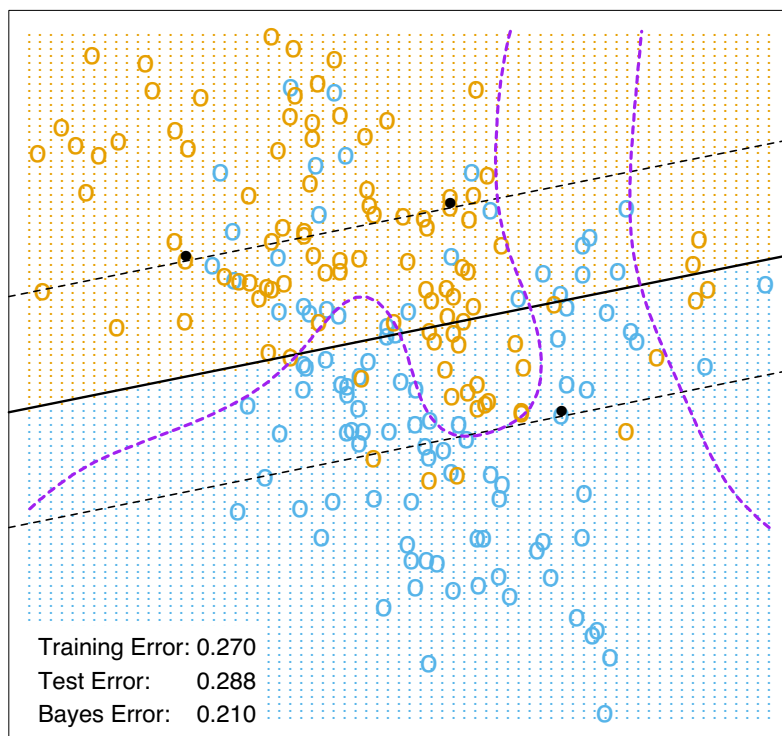
RBF
Kernel

$$k(x, x') = e^{-\frac{\|x - x'\|^2}{2\sigma^2}}$$

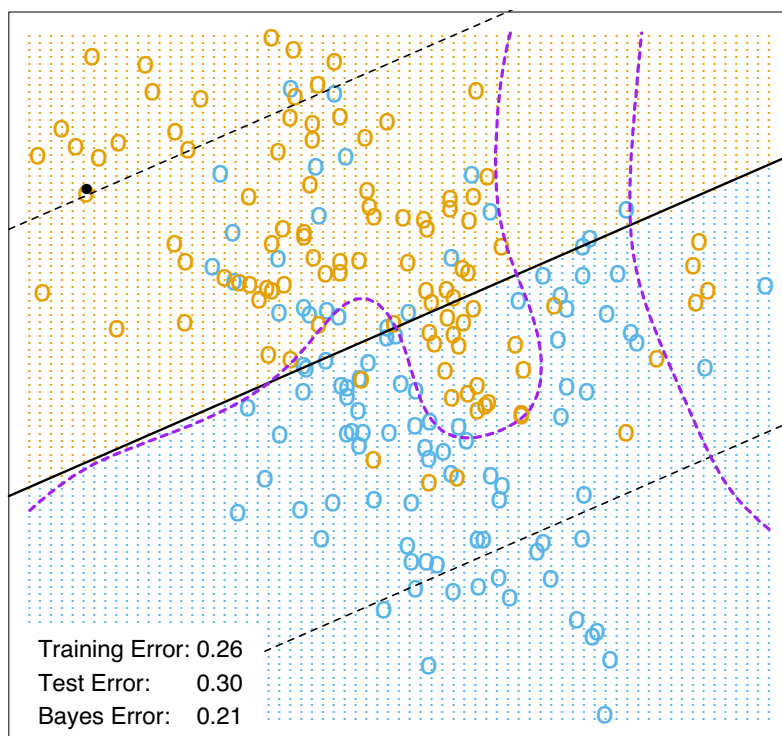
$$f(x) = \sum \alpha_i K(x_i^i, x) y_i + b$$

$\uparrow$
 RBF





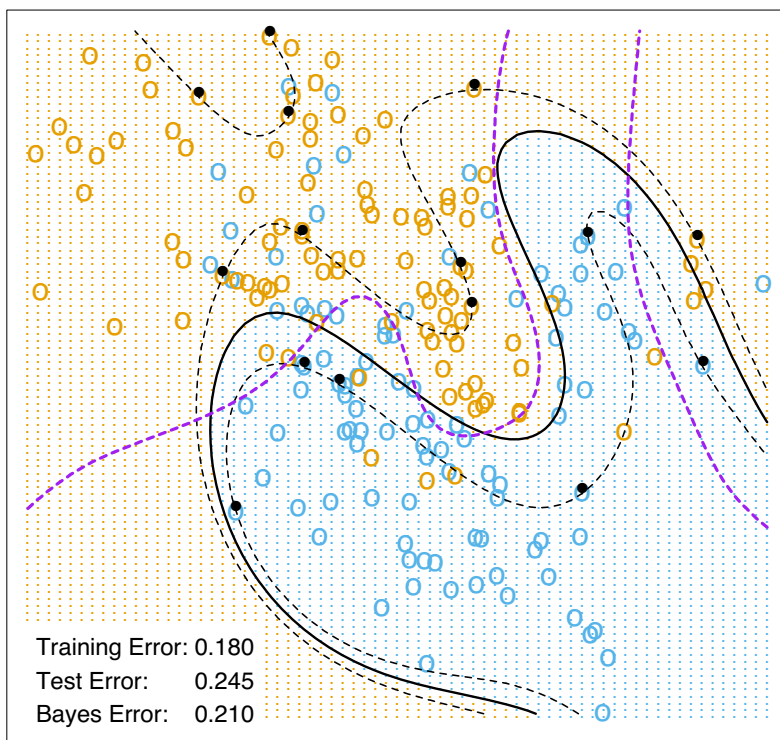
$C = 10000$



$C = 0.01$

FIGURE 12.2. The linear support vector boundary for the mixture data example with two overlapping classes, for two different values of C . The broken lines

SVM - Degree-4 Polynomial in Feature Space



SVM - Radial Kernel in Feature Space

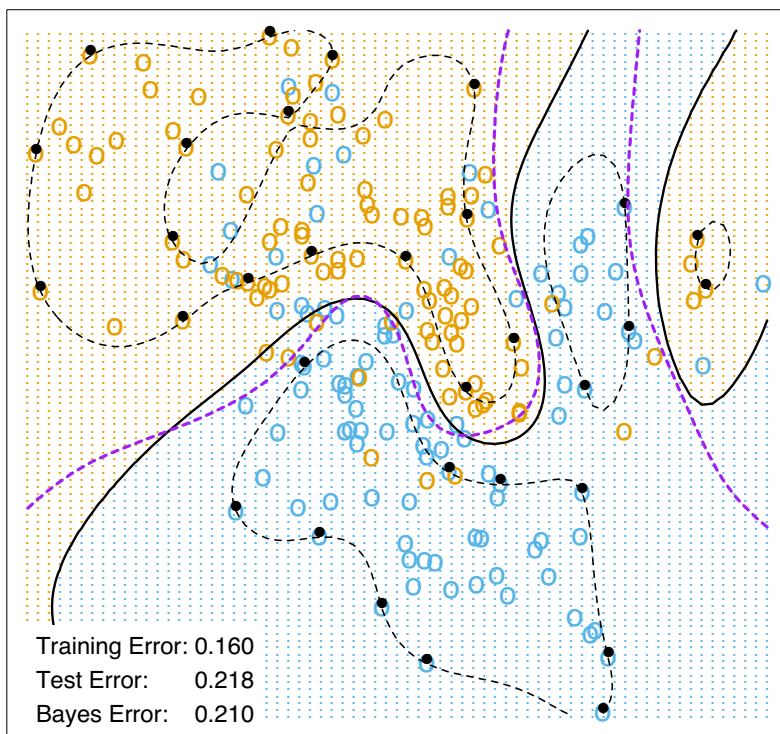


FIGURE 12.3. Two nonlinear SVMs for the mixture data. The upper plot uses a 4th degree polynomial

RKHS spaces of functions $\ni$ f classifier

infinite dim, with scalar product, complete

kernel

reproducing property (coming next)

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graph TD; RKHS["RKHS"] --> Functions["spaces of functions"]; Functions --> Classifier["f classifier"]; RKHS --> Dim["infinite dim, with scalar product, complete"]; RKHS --> Kernel["kernel"]; RKHS --> Reproducing["reproducing property (coming next)"];
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