



Lecture 6

# (Q1 today) Hw2 t.6. posted

Loss functions Expected, Bayes' Loss Bias and Variance

#### Lecture II: Prediction - Basic concepts

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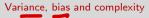
October, 2022

## Parametric vs non-parametric 🖌

#### Generative and discriminative models for classification

Generative classifiers Discriminative classifiers Generative vs discriminative classifiers

Loss functions Bayes loss



Reading HTF Ch.: 2.1-5,2.9, 7.1-4 bias-variance tradeoff, Murphy Ch.: 1., 8.6<sup>1</sup>, Bach Ch.:

Marina Meila: Prediction Concepts

 $<sup>^{-1}</sup>$ Neither textbook is close to these notes except in a few places; take them as alternative perspectives or related reading

### The "learning" problem

- Given
- ▶ a problem (e.g. recognize digits from  $m \times m$  gray-scale images)
- a sample or (training set) of labeled data

 $\mathcal{D} = \{ (x^1, y^1), (x^2, y^2), \dots (x^n, y^n) \}$ 

drawn i.i.d. from an unknown  $P_{XY}$ 

• model class  $\mathcal{F} = \{f\}$  = set of predictors to choose from

#### Wanted

- a predictor  $f \in \mathcal{F}$  that performs well on future samples from the same  $P_{XY}$ 
  - "choose a predictor  $f \in \mathcal{F}$ " = training/learning
  - "performs well on future samples" (i.e. f generalizes well) how do we measure this? how can we "guarantee" it?
  - choosing F is the model selection problem about this later

#### A zoo of predictors

- Linear regression
- Logistic regression
- Linear Discriminant (LDA)
- Quadratic Discriminant (QDA)
- CART (Decision Trees)
- K-Nearest Neighbors
- Nadaraya-Watson (Kernel regression)
- Naive Bayes
- Neural networks/Deep learning
- Support Vector Machines
- Monotonic Regression

### Loss functions

The loss function represents the cost of error in a prediction problem. We denote it by L, where  $L(\hat{y}, \hat{y}) =$  the cost of predicting  $\hat{y}$  when the actual outcome is y. Note that sometimes the loss depends on x directly. Then we would write it as  $L(y, \hat{y}, x)$ . As usually  $\hat{y} = f(x)$  or  $\operatorname{sgn} f(x)$ , we will typically abuse notation and write L(y, f(x)).

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## Least Squares (LS) loss

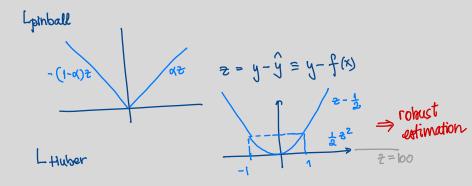
The Least Squares (LS) (or quadratic) loss function is given by

$$L_{LS}(y, f(x)) = \frac{1}{2} (y - f(x))^2$$
(5)

This loss is commonly associated with regression problems.

Example:  $L_{LS}$  is the log-likelihood of a regression problem (linear or not) with Gaussian noise.

$$L_{AE}(y,\hat{y}) = |y - \hat{y}|$$



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#### Loss functions for classification

For classification, a natural loss function is the misclassification error (also called 0-1 loss)

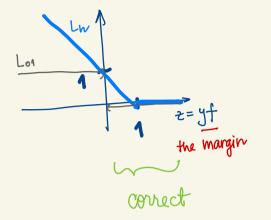
$$L_{01}(y, f(x)) = 1_{[y \neq f(x)]} = \begin{cases} 1 & \text{if } y \neq f(x) \\ 0 & \text{if } y = f(x) \end{cases}$$
(6)

Sometimes different errors have different costs. For instance, classifying a HIV+ patient as negative (a false negative error) incurs a much higher cost than classifying a normal patient as HIV+ (false positive error). This is expressed by asymmetric misclassification costs. For instance, assume that a false positive has cost one and a false negative has cost 100. We can express this in the matrix

| f(x):   | + | —   |
|---------|---|-----|
| true :+ | 0 | 100 |
| -       | 1 | 0   |

In general, when there are p classes, the matrix  $L = \begin{bmatrix} L_{kl} \end{bmatrix}$  defines the loss, with  $L_{kl}$  being the cost of misclassifying as l an example whose true class is k.

Special case: Lee = 1 iff 
$$k \neq l$$
  
In general: Lee = 0  $\mathbb{P}$  0  $\mathbb{P} \neq 1$   
flinge Loss  $L_{1}(Y, f) = \begin{cases} 1 - \mathbb{P} f & 0 \\ 1 - \mathbb{P} f & 0 \end{cases}$ 



### Expected loss and empirical loss

Objective of prediction = to minimize expected loss on future data, i.e.

minimize  $L(f) = E_{P(X,Y)}[L(Y, f(X)] \text{ over } f \in \mathcal{F}$ 

We call L(f) above expected loss.

## Example (Misclassification error $L_{01}(f)$ )

 $L_{01}(f)$  = probability of making an error on future data.

$$L_{01}(f) = P[Yf(X) < 0] = E_{P_{XY}}[1_{[Yf(X) < 0]}] = \Pr[f] \text{ makes (8)}$$
  
mistake

(7)

Lanymmetric 
$$(f) = ?$$
  
 $y \in \pm \Lambda$   $L_{+-} \neq L_{-+}$   
 $(F) = \inf_{f \in F} L(f) = best Loss with F$ 

$$\begin{aligned} \xi_{X} : & \mathcal{F}_{1} = linear classifiers \implies L(\mathcal{F}_{1}) \\ & \mathcal{F}_{2} = guadratic \longrightarrow \implies L(\mathcal{F}_{2}) \\ & X \in \mathbb{R}^{d} \\ & y \in \{\pm^{1}\}^{1} \\ & \mathcal{F}_{1} \subset \mathcal{F}_{a} \implies L(\mathcal{F}_{a}) \leq L(\mathcal{F}_{1}) \\ & \mathbb{E} \text{ repirical loss } \hat{L}(\mathcal{F}) \equiv \mathbb{E}_{\mathcal{F}_{X}}[L(Y_{1}\mathcal{F})] = \frac{1}{n} \sum_{i=1}^{n} L(y_{i}^{i}, \mathcal{f}(x^{i})) \leftarrow \text{ can be computed} \\ & \mathfrak{D}_{n} \sim \text{iid } \mathcal{P}_{Xy} \\ & \text{empirical distribution } \\ & \hat{\mathcal{F}}_{Xy} \qquad \hat{L}(\mathcal{F}) = \inf \hat{L}(\mathcal{F}) \qquad \text{sometimes electived from training} \\ & \mathbb{E}_{xy} \qquad \qquad \hat{L}(\mathcal{F}) = \inf \hat{L}(\mathcal{F}) \qquad \text{egression} \\ & \text{fe}\mathcal{F} \qquad \qquad \text{eg. Linear Regression} \\ & \text{fe}\mathcal{F} \qquad \qquad \text{eg. Linear LS Regression} \\ & \text{fe}\mathcal{F} \qquad \qquad \text{fe}\mathcal{F} \quad \qquad \text{fe}\mathcal{F}_{dat} \qquad \qquad \text{regularization} \\ & \text{Something else } (\mathcal{E}NN_{1}, \text{ Kernell regression}) \end{aligned}$$

$$\frac{2}{2} + \frac{1}{2} + \frac{1}$$

### Expected loss and empirical loss

• Objective of prediction = to minimize expected loss on future data, i.e.

minimize 
$$L(f) = E_{P(X,Y)}[L(Y, f(X)] \text{ over } f \in \mathcal{F}$$
 (7)

We call L(f) above expected loss.

L(f) cannot be minimized or even computed directly, because we don't know the data distribution P<sub>XY</sub>.

Therefore, in training predictors, one uses the empirical data distribution given by the sample  $\mathcal{D}$ .

▶ The empirical loss (or empirical error or training error) is the average loss on D

$$\hat{L}(f) = \frac{1}{n} \sum_{i=1}^{n} \mathbb{1}_{[y^{i}f(x^{i}) < 0]}$$
(8)

► Finally, the value of the optimal expected loss for our model class (this is the loss value we are aiming for) is denoted by L(F).

$$L(\mathcal{F}) = \min_{f \in \mathcal{F}} E_{P(X,Y)}[L(Y, f(X))]$$
(9)

Note that of all the quantities above, we can only know  $\hat{L}(f)$  for a finite number of f's in  $\mathcal{F}$ .

## Bayes loss

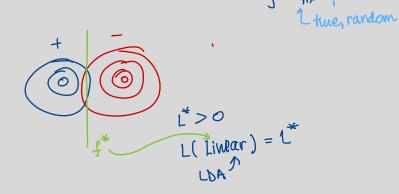
How small can the expected loss L(f) be? It is clear that

$$L(\mathcal{F}) = \min_{f \in \mathcal{F}} L(f) \geq \min_{f} L(f) = L^* = L(\mathcal{f}^*)$$
(10)

 $f_{(x)}^{*} = argminEL(y, \hat{y})$  $\hat{y}$   $R_{y|x}$ 

determ.

where  $L^*$  is taken over all possible functions f that take values in  $\mathcal{Y}$ .  $L^*$  is the absolute minimum loss for the given  $P_{XY}$  and it is called the **Bayes loss**.  $L^*$  The Bayes loss is usually not zero



### Bayes loss for (binary) classification

- Fix x and assume  $P_{Y|X}$  known. Then:
  - Label y will have probability  $P_{Y|X}(y|x)$  at this x.
  - No deterministic guess f(x) for y will make the classification error  $E_{P_Y|X=x}[L_{01}(y, f(x))]$  (unless  $P_{Y|X=x}$  is itself deterministic)
  - Best guess minimizes the probability of being wrong. This is achieved by chosing the most probable class

$$y^*(x) = \operatorname{argmax}_{Y} P_{Y|X}(y|x)$$
(11)

The probability of being wrong if we choose  $y^*(x)$  is  $1 - p^*(x)$ , where  $p^*(x) = \max_y P_{Y|X}(y|x)$ .

• The Bayes classifier is  $y^*(x)$  as a function of x and its expected loss is the Bayes loss

$$L_{01}^{*} = E_{P_{X}}[1 - p^{*}(X)] = E_{P_{X}}[1 - \max_{v} P[Y|X]]$$
(12)

This shows that the Bayes loss is a property of the problem, via L and  $P_{XY}$ , and not of any model class or learning algorithm.

#### Example

In a classification problem where the class label depends deterministically of the input, the Bayes loss is 0. For example, classifying between written English and written Japanese has (probably) zero Bayes loss.

#### Example

Consider the least squares loss and the following data distribution:  $P_{Y|X} \sim N(g(X), \sigma^2)$ . In other words, the Y values are normally distributed around a deterministic function g(X). In this case, optimal least squares predictor is the mean of Y given X, which is equal to g(X). The Bayes loss is the expected squared error around the mean, which is  $\sigma^2$ . Exercise what is the expression of the Bayes loss if  $P_{Y|X} \sim N(g(X), \sigma(X)^2)$ ?

Exercise What is the Bayes loss if (1)  $P(Y|X) \sim N((\beta^*)^T X, \sigma^2 I)$  and the loss is  $L_{LS}$ ; (2)  $P(X|Y = \pm 1) \sim N(\mu_{\pm}, \sigma^2 I)$  and the loss is  $L_{01}$  (for simplicity, assume  $X \in \mathbb{R}, \mu_{pm} = \pm 1, \sigma = 1$ ); (3) give a formula for the Bayes loss if we know  $P(X|Y = \pm 1), P(Y), Y \in \{\pm 1\}$  and the loss is  $L_{01}$ . (4) Give an example of a situation when the Bayes loss is 0.