STAT 535

10/19123

# Lecture 7

- · Variance
- · Bies-Var decomposition for Ls regression
- · Bias of Noderaya Wetson

HW2 due Mon 23 HW3 TB posted LII updated

### Lecture II: Prediction - Basic concepts

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#### Parametric vs non-parametric



#### Generative and discriminative models for classification



Generative classifiers Discriminative classifiers Generative vs discriminative classifiers



Variance, bias and complexity



Model solution

Reading HTF Ch.: 2.1-5,2.9, 7.1-4 bias-variance tradeoff, Murphy Ch.: 1., 8.6<sup>1</sup>, Bach Ch.:

<sup>&</sup>lt;sup>1</sup>Neither textbook is close to these notes except in a few places; take them as alternative perspectives or related reading

## The "learning" problem

- ▶ Given
- ▶ a problem (e.g. recognize digits from  $m \times m$  gray-scale images)
- ► a sample or (training set) of labeled data

$$\mathcal{D} = \{(x^1, y^1), (x^2, y^2), \dots (x^n, y^n)\}\$$

drawn i.i.d. from an unknown  $P_{XY}$ 

- ▶ model class  $\mathcal{F} = \{f\}$  = set of predictors to choose from
- Wanted
- lacktriangle a predictor  $f\in\mathcal{F}$  that performs well on future samples from the same  $P_{XY}$ 
  - "choose a predictor  $f \in \mathcal{F}$ " = training/learning
  - "performs well on future samples" (i.e. f generalizes well) how do we measure this? how can we "guarantee" it?
  - lacktriangledown choosing  ${\mathcal F}$  is the model selection problem about this later

## A zoo of predictors

- Linear regression
- Logistic regression
- ► Linear Discriminant (LDA)
- Quadratic Discriminant (QDA)
- CART (Decision Trees)
- K-Nearest Neighbors
- ► Nadaraya-Watson (Kernel regression)
- ► Naive Bayes
- ► Neural networks/Deep learning
- Support Vector Machines
- ► Monotonic Regression

#### Bias and variance: Preliminaries

#### Setup/What we have

- $\triangleright$  a data source  $P_{XY}$
- a class of predictors
- From  $P_{XY}$  we sample i.i.d.  $\mathcal{D}_n$  of size n. Hence  $\mathcal{D}_n \sim P_{XY}^n$ .
- of size n. Hence  $\mathcal{D}_n \sim P_n^n$ .

Pxy = Px Pyix

- ▶ A training algorithm that estimates/chooses/learns  $\hat{f}_n$  from  $\mathcal{D}_n$ .
  - lacktriangle minimize  $\hat{L}_{f\in\mathcal{F}}$  (empirical loss) Example CART, Logistic Regression and all Max Likelihood methods
  - ▶ minimize over  $f \in \mathcal{F}$  (regularized loss)

$$\hat{L}(f) + \lambda J(f) \tag{15}$$

with  $\lambda > 0$  a regularization parameter Example Ridge Regression, SVM

other training method (e.g. K-NN, LDA)

## Bias and Variance for parameter estimation

- ightharpoonup We want to estimate a parameter  $heta\in\Theta\subseteq\mathbb{R}$
- ▶ We use  $\mathcal{D}_n$  to obtain estimator  $\hat{\theta}_{\mathcal{D}_n}$  which is a function of  $\mathcal{D}_n$ .
- $\triangleright \mathcal{D}_n$  is random, hence so is  $\hat{\theta}_{\mathcal{D}_n}$ .
- ► Bias=  $(\hat{\theta}_{\mathcal{D}_n}) = E_{P_n^n}[\hat{\theta}_{\mathcal{D}_n}] \theta$
- ightharpoonup Variance=  $Var_{P^n}(\hat{\theta}_{\mathcal{D}_n})$

Both Bias and Variance are computed under the distribution from which we sampled  $\mathcal{D}_n$ , denoted by  $P^n$ .

\_\_ML

Example Estimating  $\underline{\mu}, \underline{\sigma}^2$  for  $N(\underline{\mu}, \sigma^2), \ \mathcal{D}_n = \{x_{1:n}\} \subset \mathbb{R}$ 

$$\hat{\mu} = \frac{1}{n} \sum_{i} x^{i} \tag{16}$$

$$Bias(\hat{\mu}) = E[\hat{\mu} - \mu] = \mu - \mu = 0 \quad \hat{\mu} \text{ is unbiased}$$
 (17)

$$Var(\hat{\mu}) = \sigma^2/n, \quad \sim \frac{1}{W} \sim \sqrt{2}$$
 (18)

$$\frac{\hat{\sigma}^2}{=} = \frac{1}{n} \sum_i (x^i - \hat{\mu})^2 \qquad \qquad \sqrt{\frac{1}{W}} \sqrt{C^2}$$
 (19)

$$Bias(\hat{\sigma}^2) = E[\hat{\sigma}^2 - \sigma^2] = \frac{n-1}{n}\sigma^2 - \sigma^2 = -\frac{1}{n}\sigma^2 \quad \hat{\sigma}^2 \text{ is biased}$$
 (20)

$$\hat{\sigma}^2 \sim \frac{\sigma^2}{n-1} \chi_{n-1}^2 \tag{21}$$

$$Var(\hat{\sigma}^2) = 2\sigma^2 \tag{22}$$

## Bias and Variance in Supervised Learning/Prediction

#### Similarities

- wanted f lacktriangle We use  $\mathcal{D}_n$  to estimate  $\hat{f}_n \in \mathcal{F}$
- $\triangleright \mathcal{D}_n$  is random, hence so if  $\hat{f}_n$ .
- ▶ Bias and variance are properties of  $\mathcal{F}$ , and depend on nExercise Consider linear regression  $f(x) = \beta^T x$ , with  $N(0, \sigma^2)$  noise. What are the bias and variance of XNN(O, UXZI)

#### this predictor? Differences

- $\sqrt{1}$ .  $\hat{f}$  is a function
  - $\sqrt{2}$ . We are interested in the predictions and not the parameters of  $\hat{f}$ .
  - We don't always assume f<sup>true</sup> exists.
- Several proposals to define bias and variance exist.
- What we need to know in this course/usually is qualitative

Jariance for J= model class '  $\rightarrow E[\hat{f}_{\mathfrak{D}_{n}}^{(x)}]$  for  $x \in X$ single number Var (fan(x))  $\mathbf{E}_{\mathbf{R}}\left[\mathbf{Var}_{\mathbf{P}_{\mathbf{X}\mathbf{Y}}}^{\mathbf{P}_{\mathbf{X}\mathbf{Y}}}\right]\in\left[0,0\right]$ avg over 1 future x5 avg over n data points

## Two definitions for bias in ML

- 1. Assuming f<sup>true</sup> exists
  - "Classical" framework
  - Typical example: Least Squares loss
- 2. (No assumption of  $f^{true}$ ) Bias is (in)ability of  $\mathcal{F}$  to fit the training set  $\mathcal{D}_n$  (i.e. to make  $\hat{L}=0$ )
- 3. In both cases, Variance is the variance of predictor f(x) averaged over X

## The Bias-Variance decomposition for $L_{LS}$

Assume true model P<sub>Y|X</sub>

$$y = f(x) + \epsilon$$
 with  $\epsilon \sim iid, E[\epsilon] = 0$ ,  $Var(\epsilon) = \sigma^2, y, f(x), \epsilon \in \mathbb{R}$  (23)

•  $\hat{f}_n$  is estimated from  $\mathcal{D}_n$ 

$$MSE(x) = E_{P_{XY}^{n}} \left[ \left( \hat{f}_{n}(x) - f^{true}(x) \right)^{2} \right]$$

$$= E_{P_{XY}^{n}} \left[ \left( \hat{f}_{n}(x) - E_{P_{XY}^{n}}[\hat{f}_{n}(x)] + \left( E_{P_{XY}^{n}}[\hat{f}_{n}(x)] - f^{true}(x) \right)^{2} \right]$$

$$= \underbrace{E_{P_{XY}^{n}}}_{XY} \left[ \left( \hat{f}_{n}(x) - E_{P_{XY}^{n}}[\hat{f}_{n}(x)] \right)^{2} \right] + \underbrace{E_{P_{XY}^{n}}}_{\text{deterministic}} \underbrace{\left[ \left( E_{P_{XY}^{n}}[\hat{f}_{n}(x)] - f^{true}(x) \right)^{2}}_{\text{Bias}^{2}(\hat{f}_{n}(x))} + \underbrace{\left( E_{P_{XY}^{n}}[\hat{f}_{n}(x)] - f^{true}(x) \right) \left( \hat{f}_{n}(x) - E_{P_{XY}^{n}}[\hat{f}_{n}(x)] \right)}_{=0}$$

$$(24)$$

- Note that  $MSE(x) = E_{P_{Y|X}}[L_{LS}(y, \hat{f}_n(x))]$  Exercise Prove this Integrating over all  $x \in \mathbb{R}$  w.r.t  $P_X$

$$E_{P_X}[MSE(x)] \equiv E_{P_X}[E_{P_{Y|X}}[L_{LS}(y,\hat{f}_n(x))]] = E_{P_X}[Var(\hat{f}_n(x))] + E_{P_X}[Bias^2(\hat{f}_n(x))]$$
(28)

Bias-Variance Decomposition of  $L_{LS}$ :  $L_{LS} = Var + Bias^2$ 

# larina Meila: Lecture II.1

## Lecture Notes II.1 – Bias and variance in Kernel Regression

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An elementary analysis 

LT. 1 for proof

Bias, Variance and h for  $x \in \mathbb{R}$ 

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Bias, Variance and h for  $x \in \mathbb{R}$ 

The bias of  $\hat{y}$  at x is defined as  $E_{P_X^n}E_{P_{\varepsilon}^n}[\hat{y}(x) - f(x)]$ .

$$E_{P_X^n}E_{P_{\varepsilon}^n}[\hat{y}(x) - f(x)] = h^2\sigma_b^2\left(\frac{f'(x)p_X'(x)}{p_X(x)} + \frac{f''(x)}{2}\right) + o(h^2)$$

The variance  $\hat{y}$  at x is defined as  $Var_{P_v^0P_z^0}(\hat{y}(x))$ .

$$Var_{P_X^n}P_{\varepsilon}^n(\hat{y}(x)) = \frac{1}{nh}\sigma^2 + o\left(\frac{1}{nh}\right). \tag{9}$$

y=f00)+8

The MSE (Mean Squared Error) is defined as  $E_{P_X^n} E_{P_{\varepsilon}^n} \left[ (\hat{y}(x) - f(x))^2 \right]$ , which equals

$$MSE(x) = \mathbf{bias}^2 + \mathbf{variance}^{\P} = h^4 \sigma_b^4 \left( \frac{f'(x)p_X'(x)}{p_X(x)} + \frac{f''(x)}{2} \right) + \frac{\gamma_b^2}{nh} \sigma^2 + \dots$$
 (10)

$$\begin{cases} y^2 = \int_b^2 b(z)dz & T_b^2 = \int_b^2 b(z)z^2dz \\ \mathbb{R}^d & \int_b^d \int_b^d \frac{dz}{dz} & \int_b^d \frac{dz}{dz} &$$

<sup>2</sup>After []

Remember: f= weighted ang of y' for neighbors of x f"<0, f=0 data x' symmetric  $\hat{f}_{(x)} f_{(x)} > 0$ around x

Border effect met, 1'>0 more P(X) P(X) =0 neighbors >0 this side

#### Optimal selection of h

If the MSE is integrated over  $\mathbb{R}$  we obtain the MISE  $\int_{\mathbb{R}} MSE(x)p_X(x)dx$ . The kernel width h can be chosen to minimize the MISE, for fixed  $f, p_X$  and b. We set to 0 the partial derivative

$$\frac{\partial MISE}{\partial h} = h^3 \left( \frac{}{nh^2} \right) - \frac{(}{nh^2} = 0. \tag{11}$$

It follows that  $h^5 \propto \frac{1}{n}$ , or

$$h \propto \frac{1}{n^{1/5}}.\tag{12}$$

In d dimensions, the optimal h depends on the sample size n as

$$h \propto \frac{1}{n^{1/(n+4)}}.\tag{13}$$

## Case 2: Bias as model (mis)fit

- ▶ If no  $f^{true}$  assumed, bias measures the (in)ability of the model class  $\mathcal{F}$  to fit the data  $\mathcal{D}_n$ .
- ▶ Better fit ⇔ less bias
- We measure the fit by the loss L associated with the task, i.e  $\hat{L}(\hat{f}_{\mathcal{D}_n}, \mathcal{D}_n)$
- ▶ Bias( $\mathcal{F}$ )=  $E_{P(X,Y)^n}[\hat{L}(\hat{f}_{\mathcal{D}_n},\mathcal{D}_n)]$  (hence, bias is expected empirical loss).
- ▶ Richer or more complex models classes have less bias
   Example Bias( Linear ) > Bias( Quadratic )
   Example Bias( 1-NN ) < Bias( K-NN ), for K > 1
- Example Bias (Linear)? Bias (K-NN) depends on  $P_{XY}$ !
  - In modern ML we consider sequences of model classes that can be ordered
    - by inclusion

$$\mathcal{F} \subset \mathcal{F}'$$
 then  $\mathsf{bias}(\mathcal{F}) \ge \mathsf{bias}(\mathcal{F}')$  (29)

Example Linear  $\subset$  Quadratic, ... CART( L leaves )  $\subset$  CART( L+1 leaves) ..., Neural net (L layers)  $\subset$  ...

by complexity

$$\mathsf{complexity}(\mathcal{F}) \, \leq \, \mathsf{complexity}(\mathcal{F}') \quad \mathsf{then} \, \, \mathsf{bias}(\mathcal{F}) \geq \mathsf{bias}(\mathcal{F}') \tag{30}$$

Example . . . complexity(Kernel(h))  $\nearrow$  for  $h \downarrow$ , complexity(Ridge Regression, Lasso( $\lambda$ ))  $\uparrow$  for  $\lambda \downarrow$ , complexity(Linear with margin R)  $\uparrow$  for  $R \downarrow$ 

► Larger data are harder to fit (hence more bias on average)<sup>3</sup>

<sup>&</sup>lt;sup>3</sup>Not trivial, to find a reference.

## Case 2: Bias as model (mis)fit

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- Example Bias( Linear ) ? Bias( K-NN ) depends on  $P_{XY}$ !

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## Sampling variance

- ▶ Intuition: if we draw two different data sets  $\mathcal{D}, \mathcal{D}' \sim P_{XY}$  (from the same distribution) we will obtain different predictors f, f'. Variance measures how different the predictions of f, f' can be on average.
- ▶ Variance at  $x = Var_{P_{XY}^n}(\hat{f}_{\mathcal{D}_n}(x))$ , where the randomness is over the sample  $\mathcal{D}_n$
- ▶ Variance associated with predictor class  $\mathcal{F}$  is the expectation over  $P_X$  of the variance at x, i.e  $E_{P_X}[Var_{P_X^n}(\hat{f}_{\mathcal{D}_n}(x))]$
- ▶ Variance depends on n,  $\mathcal{F}$ , and the data distribution  $P_{\chi\gamma}$  Exercise If  $P_{\gamma|\chi}$  is deterministic for all x, does it mean that the variance is 0?
- Richer model classes are subject to more variance

$$\mathcal{F} \subset \mathcal{F}'$$
 then  $Var(\mathcal{F}) \leq Var(\mathcal{F}')$  for any  $f^*$ 

## Variance, bias and model complexity

- Synonyms: rich class = complex model = flexible model = high modeling power = many degrees of freedom = many parameters
- ightharpoonup Evaluating the model complexity<sup>4</sup>/number of free parameters of a model class  $\mathcal F$  is usually a difficult problem!

Non-parametric models # parameters depends on  $P_{XY}$ , smoothing parameter and n Parametric models # parameters NOT always equal to the number of parameters of f!

Example the classifier  $f(x) = \operatorname{sgn}(\alpha x), x, \alpha \in \mathbb{R}$  depends on one parameter  $\alpha$  but has  $\infty$  degrees of freedom<sup>5</sup>!

Example the linear classifier and regressor on  $\mathbb{R}^d$  has (no more than) n+1 degrees of freedom

Example the complexity of a two layer neural net with m fixed is not known (but there are approximation results); the number of weights in f is obviously (m+1)(n+1)+1

Example For K-NN, the variance increases when K decreases

Example For pruned Decision Tree, the variance increases whith the number of levels

- ▶ The variance of a predictor increases with the complexity of  $\mathcal{F}$ .
- But complexity is the opposite of bias, so bias decrease with the complexity of F
- ► This is known as the Bias-Variance tradeoff

<sup>&</sup>lt;sup>4</sup>There are several definitions of model complexity, but this holds for all definitions I know

<sup>&</sup>lt;sup>5</sup>See VC-dimension later

## The Bias-Variance tradeoff

Wanted property (for an $\mathcal{F}$ )	unwanted consequence of $\mathcal F$ not satisfying this property	what to do
to fit $\mathcal{D}$ well to be robust to sampling noise	Bias Variance	increase complexity decrease complexity

The bias-variance tradeoff is the observation that the better a predictor class  $\mathcal{F}$  is able to fit any given sample, the more sensitive the selected f will be to sampling noise. In this course we will learn some ways of balancing these desired properties (or these undesired consequences).

## Examples, examples. . .

## Example (K-nearest neighbor classifiers)

The 1-NN can fit any data set perfectly (every data point is it's own nearest neighbor). But for K>1, the K-NN may not be able to reproduce any pattern of  $\pm 1$  in the labels. Hence its bias is larger than the bias of the 1-NN classifier. With the variance, the opposite happens: as K the number of neighbors increases, the decision regions of the K-NN classifier become more stable to the random sampling effects. Thus, the variance decreases with K.

## Example (Linear vs quadratic vs cubic . . . predictors)

The quadratic functions include all linear functions, the cubics include all quadratics, and so on. Linear classifiers will have more bias (less flexibility) than quadratic classifiers. On the other hand, the variance of the linear classifier will be lower than that of the quadratic. The case of regression is even more straightforward: if we fit the data with a higher degree polynomial, the fit will be more accurate, but the variation of the polynomial f(x) for x values not in the training set will be higher too.

#### Example (Kernel regression)

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## Examples, examples... (2)

The bias-variance tradeoff can be observed on a continuous range for **kernel regression**. When the kernel width h is near 0, f(x) from Lecture 1, equation (25) will fit the data in the training set exactly [Exercise: prove this], but will have high variance. When h is large,  $f(x^i)$  will be smoothed between  $x^i$  and the other data points nearby, so it may be some distance from  $y^i$ . However, precisely because f(x) is supported by a larger neighborhood, it will have low variance. [Exercise: find some intuitive explanations for why this is true] Hence, the smoothness parameter h controls the trade-off between bias and variance.

#### Example (Regularization)

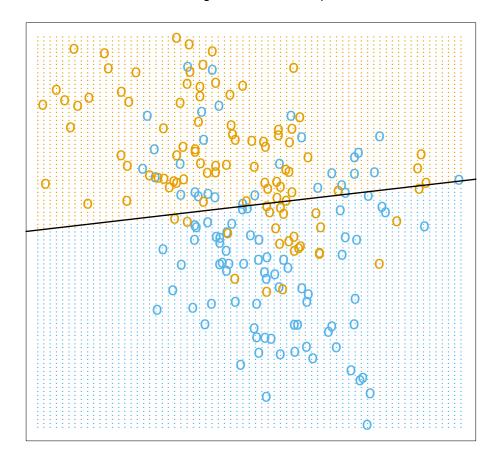
The same can be observed if one considers equation  $(\ref{eq:initial})$ . For  $\lambda=0$ , one choses f that best fits the data (minimizes  $\hat{L}$ . For  $\lambda\to\infty$ , f is chosen to minimize the penalty J, disregarding the data completely. The latter case has 0 variance, but very large bias. Between these extreme cases, the parameter  $\lambda$  controls the amount in which we balance fitting the data (variance) with pulling f towards an a-priori "good" (bias).

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- ▶ Bias and variance are properties of the model class  $\mathcal{F}$  (sometimes toghether with the learning algorithm more about this later). They are not properties of the parameters of f (e.g  $\beta$ ), and not of a particular  $f \in \mathcal{F}$ .
- ▶ Variance decreases to 0 with *n*, but bias may not. This implies that for larger sample sizes *n*, the trade-off between variance and bias changes, and typically the "best" trade-off, aka the best model, will have larger complexity.
- ▶ Overfitting= is the situation of small bias and too much variance (i.e.  $\mathcal{F}$  is too complex). In practice, if a learned predictor f has low  $\hat{L}(f)$  but significantly higher L(f), we say that the model has *overfit* the data  $\mathcal{D}$ . (Of course we cannot know L(f) directly, and a significant amount of work in statistics is dedicated to predicting L(f) for the purpose of chosing the best model.)
- ▶ Underfitting=bias is too high, or the model is too simple (a.k.a has too few degrees of freedom). [Exercise: what do you expect to see w.r.t.  $\hat{L}(f)$  v.s. L(f) for an underfitted model?]

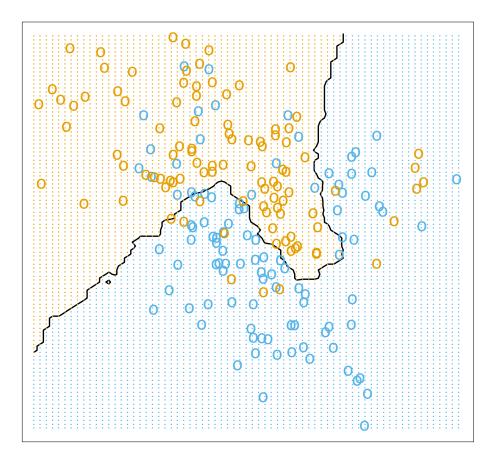
Complexity, even though there are variations in its definition, and although it is not known exactly for most model classes, is at the core of learning theory, the part of statistical theory that gives provable results about the expected loss of a predictor.

#### Linear Regression of 0/1 Response



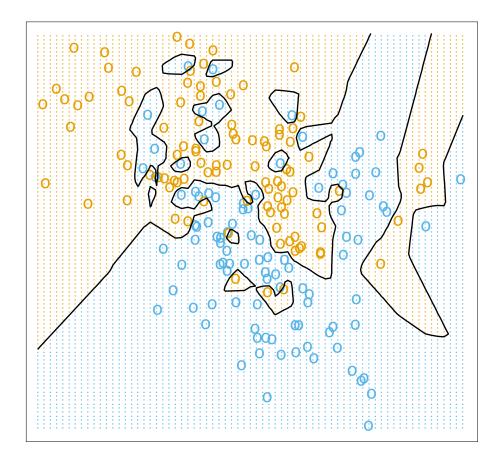
**FIGURE 2.1.** A classification example in two dimensions. The classes are coded as a binary variable (BLUE = 0, ORANGE = 1), and then fit by linear regression. The line is the decision boundary defined by  $x^T \hat{\beta} = 0.5$ . The orange shaded region denotes that part of input space classified as ORANGE, while the blue region is classified as BLUE.

### 15-Nearest Neighbor Classifier



**FIGURE 2.2.** The same classification example in two dimensions as in Figure 2.1. The classes are coded as a binary variable (BLUE = 0, ORANGE = 1) and then fit by 15-nearest-neighbor averaging as in (2.8). The predicted class is hence chosen by majority vote amongst the 15-nearest neighbors.

## 1-Nearest Neighbor Classifier



**FIGURE 2.3.** The same classification example in two dimensions as in Figure 2.1. The classes are coded as a binary variable (BLUE = 0, ORANGE = 1), and then predicted by 1-nearest-neighbor classification.

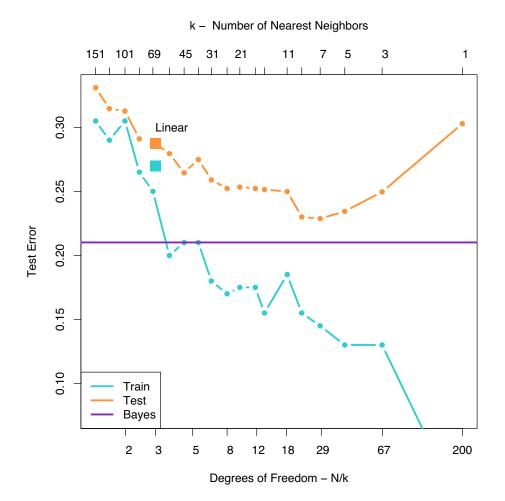


FIGURE 2.4. Misclassification curves for the simulation example used in Figures 2.1, 2.2 and 2.3. A single training sample of size 200 was used, and a test sample of size 10,000. The orange curves are test and the blue are training error for k-nearest-neighbor classification. The results for linear regression are the bigger orange and blue squares at three degrees of freedom. The purple line is the optimal Bayes error rate.

## **Bayes Optimal Classifier**

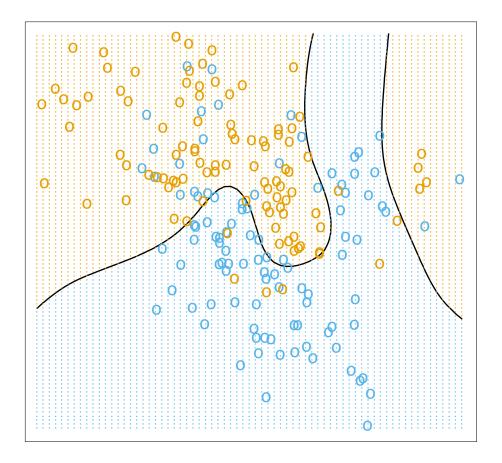


FIGURE 2.5. The optimal Bayes decision boundary for the simulation example of Figures 2.1, 2.2 and 2.3. Since the generating density is known for each class, this boundary can be calculated exactly (Exercise 2.2).

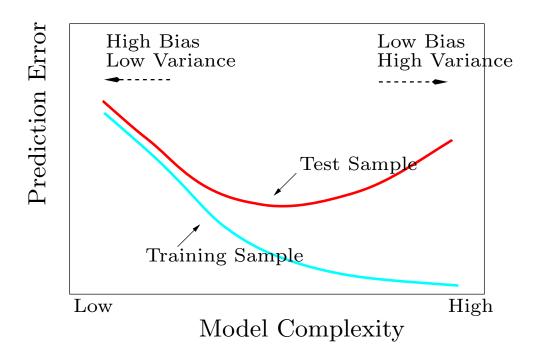
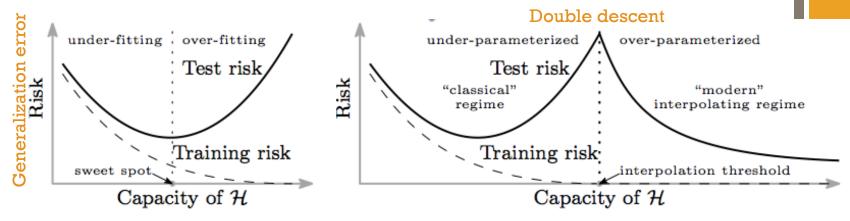


FIGURE 2.11. Test and training error as a function of model complexity.

## +

# What is observed



Belkin, Hsu, Ma, Mandal 2018

- Classical regime p < N
- Modern/Deep Learning/High dimensional regime N > n
  - Think N fixed, p increases, gamma=p/N
  - Training error = 0 (interpolation)
  - Test error decreases with p (or gamma)