

STAT 534  
Lecture 9  
**Markov Chains**  
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Scribes:

## 1 Background

(Discrete time) **Markov chains**: a term used to represent a stochastic process

Stochastic process  $X_{t \in \mathbb{Z}}$

- A collection of random variables  $X_t$  ( $t$  is an index) contained in some state space  $S$ 
  - E.g.  $t = \text{time}$
- $\mathbb{Z}$  is the set of positive integers

Going to assume the state space  $S$  is finite

- Is a set of states which  $X_t$  can take for  $X_t \in S$

We're going to assume we can describe this situation by the Markov property

- Says for any  $t \in \mathbb{Z}$ , we have that  $X_t \perp\!\!\!\perp X_s | X_{t-1}$ , where  $s \in 1, \dots, t-1$
- Equivalent to  $X_t \perp\!\!\!\perp X_s | X_r$ 
  - Where  $s < r < t$
  - If you give me any event in the past, then it doesn't matter what happened before that event
  - Can prove this from the first statement with induction
- Probability distribution at  $X_t$  is completely defined by previous state

Markov chain is one of the simplest types of graphical models

## 2 State space S

State space S, e.g.  $S = \{1, 2, 3\}$

- These are the nodes/states

$$p_i(t) = P(X_t = i)$$

- At time t our chain is in state i
- If I'm in state t, assuming I started at t=0, weve gone through t transitions to get here
- Even if transition probabilities are well-defined, might not be easy to think about where I am after t transitions

Full probability vector =  $p(t) = (p_1(t), \dots, p_m(t))$

- m is the cardinality of the state space S;  $m = |S|$

$$\sum_{i=1}^m p_i(t) = 1$$

- = probability  $X_t$  is in the state space

$p(0)$  = initial probability

- Our model involves looking at what happened before, and coming up with a probability distribution based on that
- But nothing happens before the initial point, so this gets a special name
- To estimate this, need several chains, assume independence of the chains, etc.

Transition probabilities =  $a_{ij}(t) = P(X_t = j | X_{t-1} = i)$

- How would I write  $P(X_1, X_2, X_3)$  as a conditional (in general, not for Markov chains)

$$- = P(X_2 | X_0, X_1) P(X_1 | X_0) P(X_0)$$

Can define entire probability distribution based on 1 step transitions b/c this is a Markov chain

### 3 Transition probability matrix (TPM)

Usually denoted as A

$$[a_{ij}]_{i,j=1}^m$$

- TPM= matrix of all of these  $a_{ij}$ s, from 1 to m

$$\sum_{j=1}^m a_{ij} = 1$$

- The sum over all js of  $a_{ij} = 1$
- This is how you know its the rows that represent probability distributions
  - Each row sums to 1 if we sum over the columns
  - Rows = i, columns = j

$$a_{ij} \geq 0$$

- Any matrix that has the above form and property and the additional constraint that all  $a_{ij} \geq 0$  is called a stochastic matrix
  - b/c it defines a set of probability distributions
- No negatives: cant have negative probabilities

Rows = initial state, columns = state you wind up in

### 4 (Ir)reducibility

Reducible if  $\exists i, j \in SxS$  s.t.  $P(X_t = j | X_s = i) = 0 \forall s < t, i \neq j$

- Means if I'm ever in state i, at any time, I can't get to state j, no matter what
  - b/c this is for all  $s < t$ , this isn't for  $t-1$
  - means theres no path in the graph from i to j

When a chain is reducible, we have two disjoint subsets of the state space

- if we start in one set we stay in that set forever

## 5 Periodicity

A Markov chain is periodic if  $\exists i \in S$  s.t.  $P(X_{t+t} = i | X_t = i)$  for  $t > 0, t \neq kt_0, k = 1, 2, \dots$ , and  $t_0 > 1$

- $t_0$  and  $k$  are each any positive integer  $> 1$ ,  $t$  is any integer  $> 0$ 
  - $t \neq kt_0$  means holds for all  $t'$  that aren't multiples of  $t_0$
- starting at state  $i$ , probability of being back in state  $i$   $t$  units later
- in a general situation maybe I can get back to state  $I$  in 3 steps, or 4 steps, or whatever
- but maybe I have a weird chain w/ periodic behavior, where I can't get back to  $I$  in an odd number of steps, ever; that's a periodic chain
- the transition probability matrix  $A$  defines a periodic chain:
  - $A = \{010\}\{001\}\{100\}$
  - Is just a loop; if I start at state 1, I can only get back there in 3 steps

Aperiodic chain is not periodic

A chain that is aperiodic and irreducible and homogeneous is ergodic

- We like Markov chains to be Ergodic
- Homogeneous chains:
  - Notation were using is  $a_{ij}(t)$ , but we can drop the  $t$  b/c these transition probabilities don't depend on  $t$ ; transition matrix  $A$  isn't indexed by  $t$

## 6 Ergodicity

$p(t+1)$

- Probability distribution of all of the states at time  $t+1$
- Lets consider only  $p(t)$
- What is  $p(t+1)$  in terms of  $p(t)$ ?
  - We know state distribution at  $p(t)$ , using induction we figure out  $p(t+1)$ , and do that for all  $t$ , using the Markov property

How do I build up to  $p_j(t+1)$

- Probability I'm in state j at time t+1
- $= P(X_{t+1} = j)$
- $= \sum_{i=1}^m P(X_i) a_{ij} = \sum_{i=1}^m p_i(t) a_{ij}$ 
  - $i \neq j$
  - Is saying I could be in any of the m states at time t
  - For any of those m states  $p_i(t)$  is probability I'm in that state
  - $(a_{ij})$  = probability I go from that state to j
    - \* If I sum over all those possibilities I get the probability I'm in state j at time t
  - Probability of going from i to j, times probability of starting in i
  - Summed over all m states that you could go to j from

Can write this in vector notation, assuming these are row vectors

- $p_i(t+1) = p(t)A$ 
  - if  $p(t)$  is a probability distribution so is  $p(t+1)$  given the TPM
  - $A = \text{TPM}$

What does this imply?

- Lets say I know  $p_0$ , what can I do now? I can keep multiplying by the matrix A over and over again
  - Notation =  $p(0)A^{t+1}$
- For any generic time t, the probability vector at time t = initial probability
  - \* transition probability matrix raised to t
  - $p(t) = p(0)A^t$

Next step is to think about what happens when t is really big? Is there some kind of limit? Does this converge to something?

- $p(0)$  matters a lot at the beginning, but after many cycles it shouldn't matter much
- What happens when we take t to infinity?
- This is where the ergodic property comes in, in the form of the Ergodic theorem

## 6.1 Ergodic theorem

For any ergodic Markov chain defined by transition probability matrix  $A$ , we have that  $p(t)$  goes to some limit we call  $p^\infty$  as  $t$  goes to  $\infty$ . This is built up

through a series of facts

1.  $P^\infty A = p^\infty$ 
  - $p^\infty$  is an eigenvector of  $A$
2. For any stochastic matrix  $A$ , a vector of all 1s as a column vector,  $\mathbf{1} = (1, \dots, 1)^T$ 
  - We have  $A\mathbf{1} = \mathbf{1}$
3. Any eigenvalue has magnitude  $\leq 1$  of this stochastic matrix  $A$ 
  - $|\lambda| \leq 1$
4. If we can write  $A$  as  $XDX^{-1}$ 
  - Where  $D$  is a diagonal matrix of eigenvalues
  - Then  $A^t = XD^tX^{-1}$ 
    - Power of a matrix by  $t$ ;  $A^2 = AA$
    - Lowercase  $t$  isn't transpose!
  - If we can describe the limit of  $D^t$  as  $t$  goes to infinity, then we describe the limit  $A^t$ 
    - And  $D$  is a diagonal matrix so possibly easier to work with
5.  $D^t$  goes to a limit  $D^\infty$ 
  - where  $D^\infty$  is a matrix with 1 at the top left and 0 everywhere else
  - if max of all of the eigenvalues  $(\lambda_i) = 1$  and this is unique
    - An assumption
  - $A \in \mathbb{R}^{m \times m}$ 
    - $A$  is an  $m \times m$  matrix, so is  $X$  and  $D$
  - This tells us  $A^t \rightarrow A^\infty$ 
    - Where LHS is a matrix with all of its rows defined as  $p^\infty$ 
      - \*  $P^\infty$  is a row vector, so this is still a matrix

And we call  $p^\infty$  the stationary distribution of this Markov chain

- We get here no matter where we start from; if we run the chain long enough we converge to this distribution