# STAT 538 Lecture 5 Convex sets ©Marina Meilă mmp@stat.washington.edu

**Reading:** BV 2.1–2.3, 2.5. These notes are meant to guide the reading of BV, not to replace it.

- line segment  $\{tx_2 + (1-t)x_2 \text{ with } t \in [0,1]\}$
- affine combination ∑<sub>i</sub> t<sub>i</sub>x<sub>i</sub> with ∑<sub>i</sub> t<sub>i</sub> = 1 Can also be written as x<sub>1</sub> + ∑<sub>i=2:k</sub> t<sub>i</sub>(x<sub>i</sub> x<sub>1</sub>) with any real t<sub>2:k</sub>
  convex combination ∑<sub>i</sub> t<sub>i</sub>x<sub>i</sub> with ∑<sub>i</sub> t<sub>i</sub> = 1 and t<sub>i</sub> ≥ 0
- conic combination  $\sum_{i} t_i x_i$  with  $t_i \ge 0$
- cone  $\mathcal{C}$ : if  $x \in \mathcal{C}$  then  $tx \in \mathcal{C}$  for all t > 0
- convex set, affine set, cone, convex cone
- convex hull, affine hull, conic hull

#### Extreme points

**Krein-Milman Theorem** A bounded closed convex set (in  $\mathbb{R}^d$ ) is the closed convex hull of its extreme points. [This theorem extends to spaces of functions too.

Relative interior, (relative) boundary, (relative) closure

#### Examples of Convex sets

- 1. hyperplane  $a^T(x-x_0) = 0$
- 2. half-space  $a^T x b \ge 0$
- 3. ball, ellipsoid
- 4. second-order cone  $\{(x,t) \mid t \ge 0, ||x||_2 \le t, x \in \mathbb{R}^d\}$
- 5. polyhedron = (bounded) intersection of m half-spaces
- 6. simplex = convex hull of k + 1 affinely independent points (i.e  $x_1 x_1 x_1 x_1 x_2 x_2 x_1 x_2 x$  $x_{k+1}, x_2 - x_{k+1}, \ldots$  are linearly independent)
- 7. all symmetric matrices are an affine set and a convex set (unbounded)

- 8. all positive definite matrices are a convex cone
- 9. all stochastic matrices are a convex set
- 10. all doubly stochastic matrices are a convex set (what are its extreme points?)

#### Convex sets in probability

- 1. the parameter space of all normal distributions over  $\mathbb{R}^d$  is a convex set
- 2. the (parameter) space of all discrete distributions over some countable space X
- 3. all distributions with a fixed set of marginals
- 4. the conditional distributions of a discrete joint

Let  $X, Y \in \Omega_X \times \Omega_Y$  with  $\Omega_X = m$ ,  $|\Omega_Y| = n$  be two discrete random variables, and let  $\Theta$  be the set of all probability distributions over  $\Omega_X \times \Omega_Y$ .

That is, we define  $P_{\theta}(X = i, Y = j) = \theta_{ij}$ ; then  $\Theta = \{\theta = [\theta_{ij}]_{ij} \in [0, 1]^{m \times n}, \sum_{ij} \theta_{ij} = 1\}$ . Imagine  $\theta$  to be rearranged as a vector of dimension mn:

$$\operatorname{vec}(\theta) = \left[\theta_{11} \,\theta_{12} \dots \,\theta_{21} \,\theta_{22} \,\dots \,\theta_{mn}\right]^T \tag{1}$$

We use the *linear-fractional (or projective) function* (BV page 41)

$$f(z) = \frac{Az+b}{c^T z+d} \quad \text{dom}f = \{z|c^T z+d > 0\}$$
(2)

which maps a convex set into a convex set. Let now  $z = \text{vec}(\theta), b = 0, d = 0,$ 

$$A_{ij,i'j'} = \begin{cases} 1 & \text{if } j = j' = j_0, i' = i \\ 0 & \text{otherwise} \end{cases} \qquad c_{ij} = \begin{cases} 1 & \text{if } j = j_0 \\ 0 & \text{otherwise} \end{cases}$$
(3)

In other words,  $c^T \operatorname{vec}(\theta) = \sum_i \theta_{ij_0} = P_{\theta}[Y = j_0]$ , and row ij of A, multiplied by  $\theta$  gives  $\sum_{i',j'} A_{ij,i'j'} \theta_{i'j'} = \theta_{i,j_0} = P_{\theta}[X = i, Y = j_0]$ . Hence,  $f(\theta) = P_{\theta}[X = i|Y = j_0]$  for any  $\theta \in \Theta$  with  $P_{\theta}(Y = j_0) > 0$ . This subset of  $\Theta$  is also convex (but not closed), therefore we conclude that the set of all conditional probabilities given a fixed Y is a convex set. 5. all distributions over  $\mathbb{R}$  with E[X] in a convex set (in particular E[X] fixed,  $E[X] \ge a$ )

### Convex spaces of functions

- 1. polynomials of degree n; all polynomials
- 2.  $\{g \mid g \ge f_0\}$  with  $f_0$  fixed
- 3.  $\{g \mid \int |g|^p < a\}$  with  $p \ge 1$ ,  $a \in (0, \infty)$  (the  $L_p$  balls)
- 4. all convex functions on set X

## 1 Separating and supporting hyperplanes

**Theorem** C, D convex sets,  $C \cap D = \emptyset$ . Then, there exist a hyperplane  $a^T x - b = 0$  that separates C, D, i.e so that  $a^T x \leq b$  for any  $x \in C$  and  $a^T x \geq b$  for any  $x \in D$ .

Strict separation = one of the inequalities is strict

**Proposition** C convex closed,  $x_0 \notin C$ . Then  $x_0$  can be strictly separated from C.

**Corollary: Theorem of alternatives** (BV Example 2.21) The system of linear inequalities  $Ax \prec b$ , with  $A \in \mathbb{R}^{m \times n}$  is infeasible iff the convex sets

$$C = \{b - Ax | x \in \mathbb{R}^n\} \text{ and } D = \mathbb{R}^m_{++} = \{y \in \mathbb{R}^m | y \succ 0\}$$
(4)

do not intersect.