

Homework problems  
(more problems will be added as we go along)

Stat 591, A17

1. For a stationary random field  $Z(s)$ ;  $s \in D \subseteq R^2$ , observed at sites  $s_1, \dots, s_n$ , derive the unbiased linear estimator with the smallest variance.  
*Hint:* Use a Lagrange multiplier to enforce the unbiasedness conditions.
2. For a stationary random field  $Z(s)$ ;  $s \in D \subseteq R^2$ , observed at sites  $s_1, \dots, s_n$ , show that the universal kriging estimator for  $A(s) = a^T \begin{pmatrix} 1 \\ s \end{pmatrix}$  is unbiased.
3. Compare the variability of simple and ordinary kriging (this can either be done theoretically or by designing an appropriate simulation study).
4. Write R-code to put contours of a kriged surface on a grey-scale background of kriging standard errors.
5. Design a study to compare the plug-in estimate of kriging variance to the real variance of the predictor at a single point. (You do not need to implement the study, just execute a thoughtful design—see also problem 6).
6. (For those who did problem 5). Implement your study from problem 5.
7. Show that a  $d$ -dimensional isotropic correlation functions satisfies  $\rho(v) \geq -\frac{1}{d}$ .
8. Consider the correlation function  $\rho(v) = 1 - v / \phi$ ;  $v \leq \phi$ . This is a valid correlation function in one dimension. Show that it is not valid in two dimensions.  
*Hint:* Consider points  $s_{ij}$  at a  $6 \times 8$  grid of size  $\phi / \sqrt{2}$ . Look at  $\text{Var} \sum a_{ij} Z(s_{ij})$  where  $a_{ij} = 1$  if  $i+j$  even, -1 otherwise.
9. Compare several spatial covariance models graphically, by choosing parameters so that the range/effective range, sill and the nugget are the same for all models.
10. Consider a 2-dimensional Gaussian process in the plane with known mean  $\boldsymbol{\mu} = (\mu_1, \mu_2)^T$  and covariance structure  $C(\mathbf{h}) = \begin{pmatrix} C_{11}(\mathbf{h}) & C_{12}(\mathbf{h}) \\ C_{21}(\mathbf{h}) & C_{22}(\mathbf{h}) \end{pmatrix}$ .
  - (a) Find the kriging estimate of the process at a point  $\mathbf{s}_0$ .
  - (b) If  $\mathbf{s}_0$  is one of the points of observation, under what circumstances is the kriging estimate at that point equal to the observation?

11. Develop R code that links the variogram cloud points to the geographic map, so that clicking on a point in the cloud scatter highlights the two corresponding sites, and clicking on a site highlights all the scatter points including that site.

12. For an isotropic Higdon model with kernel  $(2\pi\phi)^{-1/2} \exp(-t^2/(2\phi))$ , determine the covariance between two locations.

13. Consider iid Gaussian random variables  $\varepsilon_i$  and define a spatial process  $Z_i$  on a finite lattice by

$$Z_i - \theta_1(Z_{N(i)} + Z_{S(i)}) - \theta_2(Z_{E(i)} + Z_{W(i)}) = \varepsilon_i,$$

where  $N(i)$  is the northern neighbor of  $i$ , etc. This is called a Gaussian simultaneously specified autoregression (SAR, Whittle (1954)).

(a) Show that for suitable  $b_{ij}$

$$Z_i = \mu_i + \sum b_{ij}(Z_j - \mu_j) + \varepsilon_i.$$

(b) Show that  $\mathbf{Z} \sim N(\boldsymbol{\mu}, \sigma^2((\mathbf{I} - \mathbf{B})^{-1}((\mathbf{I} - \mathbf{B}^T)^{-1}))$  where  $\mathbf{B} = (b_{ij})$ .

(c) Show that this model is equivalent to a CAR process.

14. Using pseudolikelihood, determine how to estimate the parameters of an Ising model on a finite rectangle lattice.

15. Apply the method in problem 14 to the data in

<http://www.stat.washington.edu/peter/book.data/set5>

indicating the location of spotted wilt (a disease of a tomato plant) on a 24 by 60 field of plants (for example, the second plant from the right in row 1 is diseased).

16. (Borrowed from Brian Reich, NCSU) The data set

<http://www4.stat.ncsu.edu/~reich/st733/NARCCAP.RData>

contains, for each of 802 spatial locations in eastern US, elevation, lat/long, and median annual maximum precipitation from 1968-1999 ( $Y_{\text{past}}$ ) and from 2038-2070 ( $Y_{\text{future}}$ ), obtained from a regional climate model.

(a) Fit a trend in terms of  $Y_{\text{future}}$  and elevation.

(b) Add appropriate functions of latitude and longitude to the model in (a).

Which model do you prefer, and why?

17. Fit a Matérn covariance to the data set in problem 16. Do you think an exponential covariance would be sufficient? Is there evidence of a nugget?

You may also submit solutions to the problems in any practicum that you have not used to satisfy the practicum report requirement. The set of problems in a practicum counts as ONE homework problem.

