

Bayesian Inference for Poisson Line Cluster Point Processes

Farzaneh Safavimanesh

Joint work with:

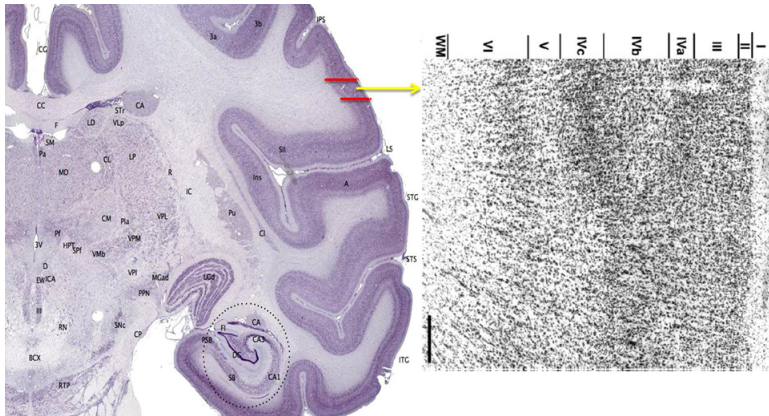
Jesper Møller, Jakob G Rasmussen

Department of Mathematical Sciences, Aalborg University, Denmark
Centre for Stochastic Geometry and Advanced Bioimaging (CSGB), Denmark

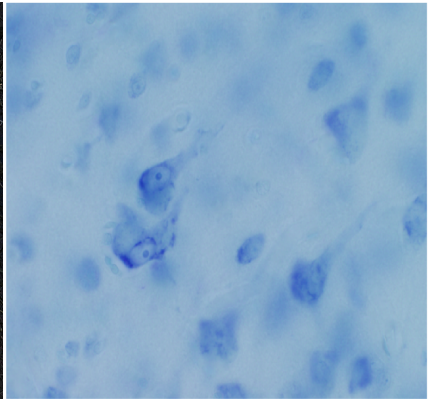
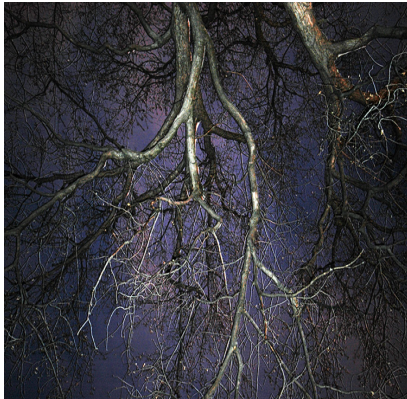
June 24, PASI 2014, Búzios, RJ, Brazil

Minicolumns; To Be or Not?

A columnar anisotropy in 3D point patterns



Minicolumns; From Reality to Availability!



The Real World

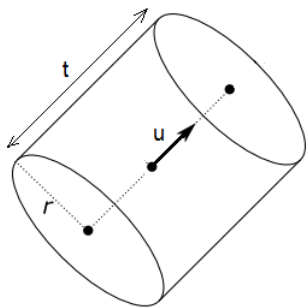


The Artificial World

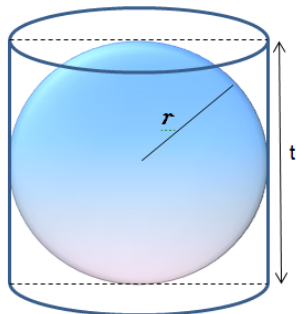
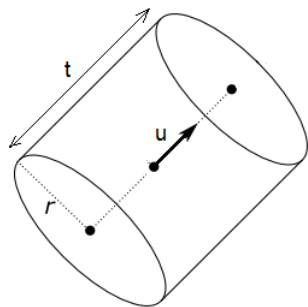
Outline

- 1 Cylindrical K -function
 - Definition
 - Non-parametric Estimation
 - Edge effects
 - Application
- 2 Poisson Line Cluster Point Processes (PLCPP)
 - Definition
 - Intensity and rose of directions
 - Moments
 - Densities for the PLCPP and a finite version of the PLCPP
 - Simulation based Bayesian inference

Cylindrical K -function: Definition



Cylindrical K -function: Definition



Cylindrical K -function vs Spherical (Ripley's) K -function

Definition

- $W \subset \mathbb{R}^d$: an arbitrary Borel set with $0 < |W| < \infty$
- For $\mathbf{u} \in \mathbb{S}_+^{d-1}$, the *cylindrical K -function in the directions $\pm \mathbf{u}$* is defined as

$$K_{\mathbf{u}}(r, t) = \frac{1}{\rho^2 |W|} \mathbb{E} \sum_{\substack{\neq \\ \mathbf{x}_1, \mathbf{x}_2 \in \mathbf{X}}} \mathbf{1}[\mathbf{x}_1 \in W, \mathbf{x}_2 - \mathbf{x}_1 \in C_{\mathbf{u}}(r, t)], \quad r, t > 0$$

- $C(r, t)$: the d -dimensional cylinder with midpoint \mathbf{o} , radius $r > 0$, and height $2t > 0$ in the direction along the x_d -axis.

Properties

- $\rho K_u(r, t)$: the mean number of further points in the cylinder with radius r , height t , direction u , and midpoint at ξ , conditional on that X has a point at the location ξ

Properties

- $\rho K_u(r, t)$: the mean number of further points in the cylinder with radius r , height t , direction u , and midpoint at ξ , conditional on that X has a point at the location ξ
- Does not depend on the choice of W because of stationarity of X

Properties

- $\rho K_u(r, t)$: the mean number of further points in the cylinder with radius r , height t , direction u , and midpoint at ξ , conditional on that X has a point at the location ξ
- Does not depend on the choice of W because of stationarity of X
- For $d = 3$, a relationship with the space-time K -function in Diggle *et al* (2009).

Non-parametric Estimation

$$\hat{K}_{\mathbf{u}}(r, t) = \frac{1}{\hat{\rho}^2} \sum_{\mathbf{x}_1, \mathbf{x}_2 \in \mathbf{y}}^{\neq} w(\mathbf{x}_1, \mathbf{x}_2) \mathbf{1}[\mathbf{x}_2 - \mathbf{x}_1 \in C_{\mathbf{u}}(r, t)]$$

- $\hat{\rho}^2 = n(n-1)/|W|^2$ is the usual estimate of ρ^2

Edge effects

Three possibilities:

- Translation correction factor
- Isotropic correction factor
- Combined correction factor

Our choice: the translation correction factor because:

Edge effects

Three possibilities:

- Translation correction factor
- Isotropic correction factor
- Combined correction factor

Our choice: the translation correction factor because:

- no restriction on the shape of W .

Edge effects

Three possibilities:

- Translation correction factor
- Isotropic correction factor
- Combined correction factor

Our choice: the translation correction factor because:

- no restriction on the shape of W .
- no restriction on the directions of $C_{\mathbf{u}}(r, t)$.

Edge effects

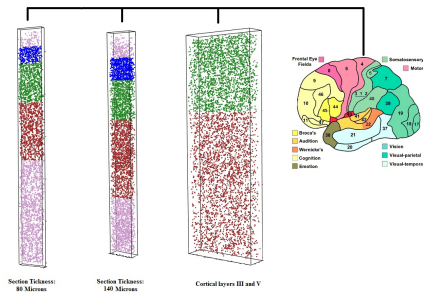
Three possibilities:

- Translation correction factor
- Isotropic correction factor
- Combined correction factor

Our choice: the translation correction factor because:

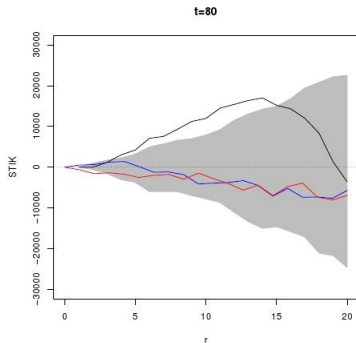
- no restriction on the shape of W .
- no restriction on the directions of $C_{\mathbf{u}}(r, t)$.
- similar results for the translation and the combined results based on the simulations

Data sets



- $|W| = 510\mu \times 138\mu \times 518\mu$
- Layer III; Brodmann area 4

Application in neuroscience: 3D Minicolumn data



- For $t = 80$, $n=999$, type I error probability = 0.026

Poisson Line Cluster Point Processes (PLCPP)

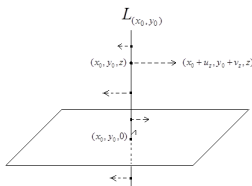
- A Cox process with columnar structure

Poisson Line Cluster Point Processes (PLCPP)

- A Cox process with columnar structure
- is used to validate the inferences on minicolumns data

Poisson Line Cluster Point Processes (PLCPP)

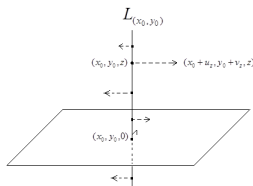
- A Cox process with columnar structure
- is used to validate the inferences on minicolumns data
- **Stepwise definition:**



- a Poisson line process $\mathbf{L} = \{l_1, l_2, \dots\}$ of (directed) lines l_i

Poisson Line Cluster Point Processes (PLCPP)

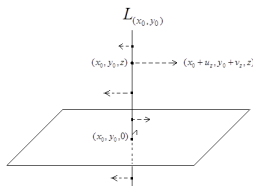
- A Cox process with columnar structure
- is used to validate the inferences on minicolumns data
- **Stepwise definition:**



- a Poisson line process $\mathbf{L} = \{l_1, l_2, \dots\}$ of (directed) lines l_i
- on each line l_i , a Poisson process \mathbf{Y}_i

Poisson Line Cluster Point Processes (PLCPP)

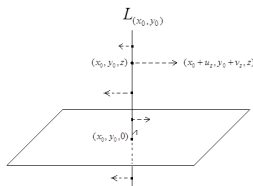
- A Cox process with columnar structure
- is used to validate the inferences on minicolumns data
- **Stepwise definition:**



- a Poisson line process $\mathbf{L} = \{l_1, l_2, \dots\}$ of (directed) lines l_i
- on each line l_i , a Poisson process \mathbf{Y}_i
- a new point process \mathbf{X}_i obtained by random displacements in \mathbb{R}^d of the points in \mathbf{Y}_i

Poisson Line Cluster Point Processes (PLCPP)

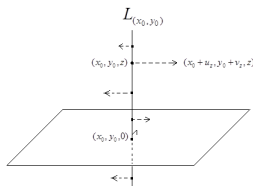
- A Cox process with columnar structure
- is used to validate the inferences on minicolumns data
- **Stepwise definition:**



- a Poisson line process $\mathbf{L} = \{l_1, l_2, \dots\}$ of (directed) lines l_i
- on each line l_i , a Poisson process \mathbf{Y}_i
- a new point process \mathbf{X}_i obtained by random displacements in \mathbb{R}^d of the points in \mathbf{Y}_i
- finally, \mathbf{X} as the superposition of all the \mathbf{X}_i .

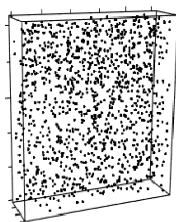
Poisson Line Cluster Point Processes (PLCPP)

- A Cox process with columnar structure
- is used to validate the inferences on minicolumns data
- **Stepwise definition:**

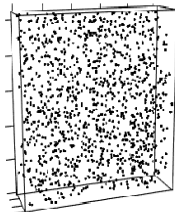


- a Poisson line process $\mathbf{L} = \{l_1, l_2, \dots\}$ of (directed) lines l_i
- on each line l_i , a Poisson process \mathbf{Y}_i
- a new point process \mathbf{X}_i obtained by random displacements in \mathbb{R}^d of the points in \mathbf{Y}_i
- finally, \mathbf{X} as the superposition of all the \mathbf{X}_i .

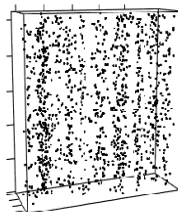
Realizations of PLCPP



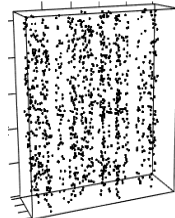
Data



CSR



PLCPP; variance=80



PLCPP; variance=20

Notation

- **The phase representation:**
 - L : is identified by a point process $\Phi \subset H \times \mathbb{S}^{d-1}$
 - H : the hyperplane perpendicular to the x_d -axis
 - \mathbb{S}^{d-1} : the unit-sphere in \mathbb{R}^d

Notation

- **The phase representation:**
 - \mathbf{L} : is identified by a point process $\Phi \subset H \times \mathbb{S}^{d-1}$
 - H : the hyperplane perpendicular to the x_d -axis
 - \mathbb{S}^{d-1} : the unit-sphere in \mathbb{R}^d
 - $l = l(\mathbf{y}, \mathbf{u}) \in \mathbf{L} \equiv (\mathbf{y}, \mathbf{u}) \in H \times \mathbb{S}^{d-1}$
 - \mathbf{u} is the direction of l
 - \mathbf{y} is the intersection point of l and H

Notation

- **The phase representation:**

- \mathbf{L} : is identified by a point process $\Phi \subset H \times \mathbb{S}^{d-1}$
 - H : the hyperplane perpendicular to the x_d -axis
 - \mathbb{S}^{d-1} : the unit-sphere in \mathbb{R}^d
- $l = l(\mathbf{y}, \mathbf{u}) \in \mathbf{L} \equiv (\mathbf{y}, \mathbf{u}) \in H \times \mathbb{S}^{d-1}$
 - \mathbf{u} is the direction of l
 - \mathbf{y} is the intersection point of l and H
- $p_{\mathbf{u}^\perp}(\mathbf{x}) = \mathbf{x} - (\mathbf{x} \cdot \mathbf{u})\mathbf{u}$: the orthogonal projection of $\mathbf{x} \in \mathbb{R}^d$ onto \mathbf{u}^\perp (the hyperplane perpendicular to \mathbf{u} and containing the origin).

PLCPP: Assumptions

- Φ : a Poisson process with intensity measure $\beta\lambda(d\mathbf{y})M(d\mathbf{u})$
 - β : a positive and finite parameter
 - M is a probability measure on \mathbb{S}^{d-1}

PLCPP: Assumptions

- Φ : a Poisson process with intensity measure $\beta\lambda(\mathrm{d}\mathbf{y})M(\mathrm{d}\mathbf{u})$
 - β : a positive and finite parameter
 - M is a probability measure on \mathbb{S}^{d-1}
- conditional on Φ , for each $(\mathbf{y}_i, \mathbf{u}_i) \in \Phi$,
 - \mathbf{Y}_i is a stationary Poisson process on $l_i = l(\mathbf{y}_i, \mathbf{u}_i)$ with positive and finite intensity α

PLCPP: Assumptions

- Φ : a Poisson process with intensity measure $\beta\lambda(d\mathbf{y})M(d\mathbf{u})$
 - β : a positive and finite parameter
 - M is a probability measure on \mathbb{S}^{d-1}
- conditional on Φ , for each $(\mathbf{y}_i, \mathbf{u}_i) \in \Phi$,
 - \mathbf{Y}_i is a stationary Poisson process on $l_i = l(\mathbf{y}_i, \mathbf{u}_i)$ with positive and finite intensity α
 - \mathbf{X}_i is a Poisson process on \mathbb{R}^d with intensity function

$$\Lambda_i(\mathbf{x}) = \alpha k_{\mathbf{u}_i^\perp}(p_{\mathbf{u}_i^\perp}(\mathbf{x} - \mathbf{y}_i)), \quad \mathbf{x} \in \mathbb{R}^d,$$

PLCPP: Assumptions

- Φ : a Poisson process with intensity measure $\beta\lambda(\mathbf{d}\mathbf{y})M(\mathbf{d}\mathbf{u})$
 - β : a positive and finite parameter
 - M is a probability measure on \mathbb{S}^{d-1}
- conditional on Φ , for each $(\mathbf{y}_i, \mathbf{u}_i) \in \Phi$,
 - \mathbf{Y}_i is a stationary Poisson process on $l_i = l(\mathbf{y}_i, \mathbf{u}_i)$ with positive and finite intensity α
 - \mathbf{X}_i is a Poisson process on \mathbb{R}^d with intensity function

$$\Lambda_i(\mathbf{x}) = \alpha k_{\mathbf{u}_i^\perp}(p_{\mathbf{u}_i^\perp}(\mathbf{x} - \mathbf{y}_i)), \quad \mathbf{x} \in \mathbb{R}^d,$$

- all the \mathbf{Y}_i 's are independent; all the \mathbf{X}_i 's are independent

PLCPP: Assumptions

- Φ : a Poisson process with intensity measure $\beta\lambda(\mathbf{d}\mathbf{y})M(\mathbf{d}\mathbf{u})$
 - β : a positive and finite parameter
 - M is a probability measure on \mathbb{S}^{d-1}
- conditional on Φ , for each $(\mathbf{y}_i, \mathbf{u}_i) \in \Phi$,
 - \mathbf{Y}_i is a stationary Poisson process on $l_i = l(\mathbf{y}_i, \mathbf{u}_i)$ with positive and finite intensity α
 - \mathbf{X}_i is a Poisson process on \mathbb{R}^d with intensity function

$$\Lambda_i(\mathbf{x}) = \alpha k_{\mathbf{u}_i^\perp}(p_{\mathbf{u}_i^\perp}(\mathbf{x} - \mathbf{y}_i)), \quad \mathbf{x} \in \mathbb{R}^d,$$

- all the \mathbf{Y}_i 's are independent; all the \mathbf{X}_i 's are independent
- the PLCPP \mathbf{X} : a Cox process with driving random intensity function $\Lambda(\mathbf{x}) = \sum_i \Lambda_i(\mathbf{x})$ for $\mathbf{x} \in \mathbb{R}^d$

PLCPP: Assumptions

- Φ : a Poisson process with intensity measure $\beta\lambda(d\mathbf{y})M(d\mathbf{u})$
 - β : a positive and finite parameter
 - M is a probability measure on \mathbb{S}^{d-1}
- conditional on Φ , for each $(\mathbf{y}_i, \mathbf{u}_i) \in \Phi$,
 - \mathbf{Y}_i is a stationary Poisson process on $l_i = l(\mathbf{y}_i, \mathbf{u}_i)$ with positive and finite intensity α
 - \mathbf{X}_i is a Poisson process on \mathbb{R}^d with intensity function

$$\Lambda_i(\mathbf{x}) = \alpha k_{\mathbf{u}_i^\perp}(p_{\mathbf{u}_i^\perp}(\mathbf{x} - \mathbf{y}_i)), \quad \mathbf{x} \in \mathbb{R}^d,$$

- all the \mathbf{Y}_i 's are independent; all the \mathbf{X}_i 's are independent
- the PLCPP \mathbf{X} : a Cox process with driving random intensity function $\Lambda(\mathbf{x}) = \sum_i \Lambda_i(\mathbf{x})$ for $\mathbf{x} \in \mathbb{R}^d$

PLCPP: Intensity and rose of directions

- **Useful for computational reason:**

to specify the distribution of the Poisson line process \mathbf{L} by (β, M) .

- **Useful for interpretation:**

to specify the distribution of the Poisson line process \mathbf{L} by (ρ_L, \mathcal{R})

- ρ_L : the intensity of \mathbf{L}
- \mathcal{R} : the rose of directions of \mathbf{L}

- ρ_L : the mean length of lines in \mathbf{L} within any region of unit volume in \mathbb{R}^d
- \mathcal{R} : the distribution for the direction of a typical line in \mathbf{L}

- ρ_L : the mean length of lines in \mathbf{L} within any region of unit volume in \mathbb{R}^d
- \mathcal{R} : the distribution for the direction of a typical line in \mathbf{L}

A one-to-one correspondence between (β, M) and (ρ_L, \mathcal{R}) :
 For any Borel set $B \subseteq \mathbb{S}^{d-1}$, [0.2]

$$\rho_L = \beta \int 1/|u_d| M(d\mathbf{u}), \quad \mathcal{R}(B) = \int_B 1/|u_d| M(d\mathbf{u}) / \int 1/|u_d| M(d\mathbf{u}).$$

A one-to-one correspondence between (ρ_L, \mathcal{R}) and (β, M) :

$$\beta = \rho_L \int |u_d| \mathcal{R}(d\mathbf{u}), \quad M(B) = \int_B |u_d| \mathcal{R}(d\mathbf{u}) / \int |u_d| \mathcal{R}(d\mathbf{u}).$$

PLCPP: Moments

Reminder: The PLCPP \mathbf{X} is a Cox process with driving random intensity Λ .

PLCPP: Moments

Reminder: The PLCPP \mathbf{X} is a Cox process with driving random intensity Λ .

$$\rho = \mathbb{E}[\Lambda(\mathbf{o})], \quad \rho^2 g(\mathbf{x}) = \mathbb{E}[\Lambda(\mathbf{o})\Lambda(\mathbf{x})], \quad \mathbf{x} \in \mathbb{R}^d.$$

We verified that

$$\rho = \alpha \rho_L$$

and

$$g(\mathbf{x}) = 1 + \frac{1}{\rho_L} \int k_{\mathbf{u}^\perp} * \tilde{k}_{\mathbf{u}^\perp}(\rho_{\mathbf{u}^\perp}(\mathbf{x})) \mathcal{R}(\mathrm{d}\mathbf{u}), \quad \mathbf{x} \in \mathbb{R}^d,$$

Thus $g > 1$, reflecting the clustering of the PLPCP

PLCPP: Densities

- $\mathbf{X}_W = \mathbf{X} \cap W$, the PLCPP restricted to a bounded region $W \subset \mathbb{R}^d$
- A finite approximation of the latent process Φ

Their densities are required for Bayesian inference

PLCPP: Densities

- $\mathbf{X}_W = \mathbf{X} \cap W$, the PLCPP restricted to a bounded region $W \subset \mathbb{R}^d$
- A finite approximation of the latent process Φ

Their densities are required for Bayesian inference

- $k_{\mathbf{u}^\perp}(\mathbf{y}) = f(\mathbf{y}|\sigma^2)$: the density for a zero-mean radially symmetric normal distribution on H with variance $\sigma^2 > 0$

PLCPP: Densities

- $\mathbf{X}_W = \mathbf{X} \cap W$, the PLCPP restricted to a bounded region $W \subset \mathbb{R}^d$
- A finite approximation of the latent process Φ

Their densities are required for Bayesian inference

- $k_{\mathbf{u}\perp}(\mathbf{y}) = f(\mathbf{y}|\sigma^2)$: the density for a zero-mean radially symmetric normal distribution on H with variance $\sigma^2 > 0$
- \mathcal{R} follows the von Mises-Fisher density $f(\cdot|\boldsymbol{\mu}, \kappa)$ with respect to the surface measure ν_{d-1} on \mathbb{S}^{d-1} :

PLCPP: Densities

- $\mathbf{X}_W = \mathbf{X} \cap W$, the PLCPP restricted to a bounded region $W \subset \mathbb{R}^d$
- A finite approximation of the latent process Φ

Their densities are required for Bayesian inference

- $k_{\mathbf{u}\perp}(\mathbf{y}) = f(\mathbf{y}|\sigma^2)$: the density for a zero-mean radially symmetric normal distribution on H with variance $\sigma^2 > 0$
- \mathcal{R} follows the von Mises-Fisher density $f(\cdot|\boldsymbol{\mu}, \kappa)$ with respect to the surface measure ν_{d-1} on \mathbb{S}^{d-1} :

$$f(\mathbf{u}|\boldsymbol{\mu}, \kappa) = c_d(\kappa) \exp(\kappa \boldsymbol{\mu} \cdot \mathbf{u}), \quad c_d(\kappa) = \frac{\kappa^{d/2-1}}{(2\pi)^{d/2} I_{d/2-1}(\kappa)}, \quad \mathbf{u} \in \mathbb{S}^{d-1},$$

I_d : the modified Bessel function of the first kind and order d

PLCPP: Densities

- Conditional on Φ , \mathbf{X}_W is absolutely continuous with respect to the unit rate Poisson process on W , with density

PLCPP: Densities

- Conditional on Φ , \mathbf{X}_W is absolutely continuous with respect to the unit rate Poisson process on W , with density

$$f(\{\mathbf{x}_1, \dots, \mathbf{x}_n\} | \Phi, \alpha, \sigma^2) = \exp\left(|W| - \int_W \Lambda(\mathbf{x} | \Phi, \alpha, \sigma^2) dx\right) \prod_{i=1}^n \Lambda(\mathbf{x}_i | \Phi, \alpha, \sigma^2)$$

for finite point configurations $\{\mathbf{x}_1, \dots, \mathbf{x}_n\} \subset W$.

PLCPP: Densities

- Conditional on Φ , \mathbf{X}_W is absolutely continuous with respect to the unit rate Poisson process on W , with density

$$f(\{\mathbf{x}_1, \dots, \mathbf{x}_n\} | \Phi, \alpha, \sigma^2) = \exp\left(|W| - \int_W \Lambda(\mathbf{x} | \Phi, \alpha, \sigma^2) dx\right) \prod_{i=1}^n \Lambda(\mathbf{x}_i | \Phi, \alpha, \sigma^2)$$

for finite point configurations $\{\mathbf{x}_1, \dots, \mathbf{x}_n\} \subset W$.

- We replace the infinite Φ by a finite approximation $\Phi_S = \Phi \cap S$ so that

$$\Lambda(\mathbf{x} | \Phi_S, \alpha, \sigma^2) = \alpha \sum_{(\mathbf{y}, \mathbf{u}) \in \Phi_S} f(p_{\mathbf{u}^\perp}(\mathbf{x} - \mathbf{y}) | \sigma^2)$$

is a finite sum.

PLCPP: Densities

- S : the set of lines hitting a bounded region $W_{\text{ext}} \supseteq W$

$$S = \{(\mathbf{y}, \mathbf{u}) \in H \times \mathbb{S}^{d-1} : l(\mathbf{y}, \mathbf{u}) \cap W_{\text{ext}} \neq \emptyset\}.$$

PLCPP: Densities

- S : the set of lines hitting a bounded region $W_{\text{ext}} \supseteq W$

$$S = \{(\mathbf{y}, \mathbf{u}) \in H \times \mathbb{S}^{d-1} : l(\mathbf{y}, \mathbf{u}) \cap W_{\text{ext}} \neq \emptyset\}.$$

- **The choice of W_{ext}**
- depends on the model and the data at hand

PLCPP: Densities

- S : the set of lines hitting a bounded region $W_{\text{ext}} \supseteq W$

$$S = \{(\mathbf{y}, \mathbf{u}) \in H \times \mathbb{S}^{d-1} : l(\mathbf{y}, \mathbf{u}) \cap W_{\text{ext}} \neq \emptyset\}.$$

- **The choice of W_{ext}**
- depends on the model and the data at hand
- to eliminate boundary effects, W_{ext} is sufficiently large so that it is very unlikely that for some line $l_i = l(\mathbf{y}_i, \mathbf{u}_i) \in \mathbf{L}$ with $(\mathbf{y}_i, \mathbf{u}_i) \notin S$, \mathbf{X}_i has a point in W .

PLCPP: Densities

- Φ_S is a Poisson process on S with intensity function

$$\chi(\mathbf{y}, \mathbf{u} | \boldsymbol{\mu}, \kappa) = \rho_L |u_d| f(\mathbf{u} | \boldsymbol{\mu}, \kappa)$$

with respect to the measure $\lambda(d\mathbf{y})\nu_{d-1}(d\mathbf{u})$

PLCPP: Densities

- Φ_S is a Poisson process on S with intensity function

$$\chi(\mathbf{y}, \mathbf{u} | \boldsymbol{\mu}, \kappa) = \rho_L |u_d| f(\mathbf{u} | \boldsymbol{\mu}, \kappa)$$

with respect to the measure $\lambda(d\mathbf{y})\nu_{d-1}(d\mathbf{u})$

- The distribution of Φ_S is absolutely continuous with respect to the distribution of a natural reference process $\Phi_{0,S}$ defined as the Poisson process on S with intensity function

$$\chi_0(\mathbf{y}, \mathbf{u}) = |u_d| \Gamma(d/2) / (2\pi^{d/2})$$

with respect to the measure $\lambda(d\mathbf{y})\nu_{d-1}(d\mathbf{u})$

PLCPP: Densities

- Φ_S is a Poisson process on S with intensity function

$$\chi(\mathbf{y}, \mathbf{u} | \boldsymbol{\mu}, \kappa) = \rho_L |u_d| f(\mathbf{u} | \boldsymbol{\mu}, \kappa)$$

with respect to the measure $\lambda(d\mathbf{y})\nu_{d-1}(d\mathbf{u})$

- The distribution of Φ_S is absolutely continuous with respect to the distribution of a natural reference process $\Phi_{0,S}$ defined as the Poisson process on S with intensity function

$$\chi_0(\mathbf{y}, \mathbf{u}) = |u_d| \Gamma(d/2) / (2\pi^{d/2})$$

with respect to the measure $\lambda(d\mathbf{y})\nu_{d-1}(d\mathbf{u})$

- The reference process corresponds to the case of an isotropic Poisson line process with unit intensity.

PLCPP: Densities

- Letting $\Phi_{0,S} = \Phi_0 \cap S$, then the density of Φ_S with respect to the distribution of $\Phi_{0,S}$ is

$$\begin{aligned}
 & f(\{(\mathbf{y}_1, \mathbf{u}_1), \dots, (\mathbf{y}_k, \mathbf{u}_k)\} | \rho_L, \boldsymbol{\mu}, \kappa) \\
 &= \exp\left(\int_S [\chi_0(\mathbf{y}, \mathbf{u}) - \chi(\mathbf{y}, \mathbf{u} | \boldsymbol{\mu}, \kappa)] \lambda(d\mathbf{y}) \nu_{d-1}(d\mathbf{u})\right) \prod_{j=1}^k \frac{\chi(\mathbf{y}_j, \mathbf{u}_j | \boldsymbol{\mu}, \kappa)}{\chi_0(\mathbf{y}_j, \mathbf{u}_j)}
 \end{aligned}$$

for finite point configurations $\{(\mathbf{y}_1, \mathbf{u}_1), \dots, (\mathbf{y}_k, \mathbf{u}_k)\} \subset S$.

PLCPP: Densities

- That is

$$f(\{(\mathbf{y}_1, \mathbf{u}_1), \dots, (\mathbf{y}_k, \mathbf{u}_k)\} | \rho_L, \boldsymbol{\mu}, \kappa)$$

$$\propto \exp\left(-\rho_L \int_{\mathbb{S}^{d-1}} |u_d| \lambda(J_{\mathbf{u}}) f(\mathbf{u} | \boldsymbol{\mu}, \kappa) \nu_{d-1}(d\mathbf{u})\right) \\
\times \prod_{j=1}^k \left[\frac{2\pi^{d/2}}{\Gamma(d/2)} \rho_L f(\mathbf{u}_j | \boldsymbol{\mu}, \kappa) \mathbf{1}[\mathbf{y}_j \in J_{\mathbf{u}_j}] \right]$$

- Our data: $\mathbf{X}_W = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$

- Our data: $\mathbf{X}_W = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$
- Independent priors on the parameters: $p(\alpha), p(\sigma^2), p(\rho_L), p(\mu), p(\kappa)$

- Our data: $\mathbf{X}_W = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$
- Independent priors on the parameters: $p(\alpha), p(\sigma^2), p(\rho_L), p(\boldsymbol{\mu}), p(\kappa)$
- The missing data: Φ_S

- Our data: $\mathbf{X}_W = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$
- Independent priors on the parameters: $p(\alpha), p(\sigma^2), p(\rho_L), p(\boldsymbol{\mu}), p(\kappa)$
- The missing data: Φ_S
- The joint density of \mathbf{X}_W and Φ_S :

$$\begin{aligned}
 & l(\alpha, \sigma^2, \rho_L, \boldsymbol{\mu}, \kappa | \{\mathbf{x}_1, \dots, \mathbf{x}_n\}, \{(\mathbf{y}_1, \mathbf{u}_1), \dots, (\mathbf{y}_k, \mathbf{u}_k)\}) \\
 & = f(\{\mathbf{x}_1, \dots, \mathbf{x}_n\} | \{(\mathbf{y}_1, \mathbf{u}_1), \dots, (\mathbf{y}_k, \mathbf{u}_k)\}, \alpha, \sigma^2) f(\{(\mathbf{y}_1, \mathbf{u}_1), \dots, (\mathbf{y}_k, \mathbf{u}_k)\} | \rho_L, \boldsymbol{\mu}, \kappa)
 \end{aligned}$$

- Our data: $\mathbf{X}_W = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$
- Independent priors on the parameters: $p(\alpha), p(\sigma^2), p(\rho_L), p(\boldsymbol{\mu}), p(\kappa)$
- The missing data: Φ_S
- The joint density of \mathbf{X}_W and Φ_S :

$$\begin{aligned}
 & l(\alpha, \sigma^2, \rho_L, \boldsymbol{\mu}, \kappa | \{\mathbf{x}_1, \dots, \mathbf{x}_n\}, \{(\mathbf{y}_1, \mathbf{u}_1), \dots, (\mathbf{y}_k, \mathbf{u}_k)\}) \\
 &= f(\{\mathbf{x}_1, \dots, \mathbf{x}_n\} | \{(\mathbf{y}_1, \mathbf{u}_1), \dots, (\mathbf{y}_k, \mathbf{u}_k)\}, \alpha, \sigma^2) f(\{(\mathbf{y}_1, \mathbf{u}_1), \dots, (\mathbf{y}_k, \mathbf{u}_k)\} | \rho_L, \boldsymbol{\mu}, \kappa)
 \end{aligned}$$

- Thus the posterior density:

$$\begin{aligned}
 & p(\alpha, \sigma^2, \rho_L, \boldsymbol{\mu}, \kappa, \{(\mathbf{y}_1, \mathbf{u}_1), \dots, (\mathbf{y}_k, \mathbf{u}_k)\} | \{\mathbf{x}_1, \dots, \mathbf{x}_n\}) \\
 & \propto l(\alpha, \sigma^2, \rho_L, \boldsymbol{\mu}, \kappa | \{\mathbf{x}_1, \dots, \mathbf{x}_n\}, \{(\mathbf{y}_1, \mathbf{u}_1), \dots, (\mathbf{y}_k, \mathbf{u}_k)\}) p(\alpha) p(\sigma^2) p(\rho_L) p(\boldsymbol{\mu}) p(\kappa).
 \end{aligned}$$

A hybrid MCMC algorithm for estimating the parameters

α and ρ_L : Gibbs updates from two gamma distributions

$$R_{\sigma^2} = \frac{p(\sigma'^2)}{p(\sigma^2)} \exp \left(\alpha \int_W \sum_{j=1}^k \left[f(\rho_{\mathbf{u}_j^\perp}(\mathbf{x} - \mathbf{y}_j) | \sigma^2) - f(\rho_{\mathbf{u}_j^\perp}(\mathbf{x} - \mathbf{y}_j) | \sigma'^2) \right] d\mathbf{x} \right)$$

$$\prod_{i=1}^n \frac{\sum_{j=1}^k f(\rho_{\mathbf{u}_j^\perp}(\mathbf{x}_i - \mathbf{y}_j) | \sigma'^2)}{\sum_{j=1}^k f(\rho_{\mathbf{u}_j^\perp}(\mathbf{x}_i - \mathbf{y}_j) | \sigma^2)},$$

$$R_{\boldsymbol{\mu}} = \frac{p(\boldsymbol{\mu}')}{p(\boldsymbol{\mu})} \exp(\rho_L [I(\boldsymbol{\mu}, \kappa) - I(\boldsymbol{\mu}', \kappa)]) \prod_{j=1}^k \frac{f(\mathbf{u}_j | \boldsymbol{\mu}', \kappa)}{f(\mathbf{u}_j | \boldsymbol{\mu}, \kappa)},$$

$$R_{\kappa} = \frac{p(\kappa')}{p(\kappa)} \exp(\rho_L [I(\boldsymbol{\mu}, \kappa) - I(\boldsymbol{\mu}, \kappa')]) \prod_{j=1}^k \frac{f(\mathbf{u}_j | \boldsymbol{\mu}, \kappa')}{f(\mathbf{u}_j | \boldsymbol{\mu}, \kappa)}.$$

Updating the missing data: The birth-death-move Metropolis-Hastings algorithm

$$R_{\text{birth}} = R_{\text{birth}}(k, \mathbf{y}, \mathbf{u}) = \frac{\rho_L \lambda(J_{\mathbf{u}}) |u_d|}{k+1} \mathbf{1}[l(\mathbf{y}, \mathbf{u}) \cap W_{\text{ext}} \neq \emptyset]$$

$$R_{\text{death}} = R_{\text{death}}(k, \mathbf{y}_j, \mathbf{u}_j) = \frac{k}{\rho_L \lambda(J_{\mathbf{u}_j}) |u_{d,j}|}$$

$$R_{\text{move}} = R_{\text{death}}(k, \mathbf{y}_j, \mathbf{u}_j) R_{\text{birth}}(k-1, \mathbf{y}'_j, \mathbf{u}'_j) = \frac{|u'_{d,j}| \lambda(J_{\mathbf{u}'_j})}{|u_{d,j}| \lambda(J_{\mathbf{u}_j})} \mathbf{1}[l(\mathbf{y}'_j, \mathbf{u}'_j) \cap W_{\text{ext}} \neq \emptyset]$$

References

- Møller, J., Safavimanesh, F. & Rasmussen, J. G. (2014). The cylindrical k -function and models for anisotropy and linear structures in spatial point patterns .
- Rafati, A., Safavimanesh, F., Dorph-Petersen, K., Rasmussen, J. G., Møller, J. & Nyengaard, J. R. (2014). The degree of columnarity: an index for spatial quantification of minicolumns in cerebral cortex .
- Safavimanesh, F. & Redenbach, C. (2014). A comparison of functional summary statistics for detencting anisotropy of three-dimensional point processes .

Thank you!