

Covariance functions, Bochner's theorem, and more

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First part based on the book “Interpolation of Spatial Data: Some Theory for Kriging” by M. L. Stein (1999)

Outline

- 1 Mean square properties, Bochner's theorem, ...
- 2 Frequentist' estimation, some practical comments
- 3 Covariance models on a sphere

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Mean square properties

- Relate covariance structure of a random field and the smoothness of its realization
- Z , a random field on \mathbb{R}^d , is mean square continuous at \mathbf{x} if

$$E\{Z(\mathbf{y}) - Z(\mathbf{x})\}^2 \rightarrow 0$$

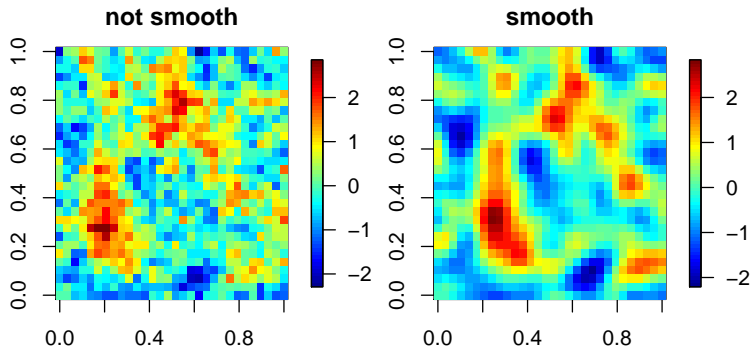
as $\mathbf{y} \rightarrow \mathbf{x}$

- For weakly stationary random field, mean square continuity iff its autocovariance function is continuous at the origin
- Mean square continuity does NOT imply continuity of its realizations

Mean square properties

- Z on \mathbb{R} is mean square differentiable at t if there exist $Z'(t) = \lim_{n \rightarrow \infty} \{Z(t + h_n) - Z(t)\}/h_n$ (in L^2) for $h_n \rightarrow 0$
- Extension to higher dimension and higher order is straightforward
- There can be analytic realizations of random field, not mean square differentiable:
 - $Z(t) = \cos(Xt + Y)$, X and Y independent, X following standard Cauchy, Y following uniform on $[0, 2\pi]$
 - All realizations are obviously analytic
 - $\text{Cov}\{Z(s), Z(t)\} = \exp(-|s - t|/2)$

Mean square smoothness



Spectral methods

- Define complex random fields: $Z(\mathbf{x}) = U(\mathbf{x}) + iV(\mathbf{x})$
- $Z(\mathbf{x}) = \sum_{k=1}^n Z_k \exp(i\mathbf{w}_k^T \mathbf{x})$, $\mathbf{w}_k \in \mathbb{R}^d$,
 Z_1, \dots, Z_n are mean 0 complex random variables with
 $E(Z_i \overline{Z_j}) = 0$ ($i \neq j$), $E|Z_i|^2 < \infty$
- Its covariance function $K(\mathbf{x}) = \sum_{k=1}^n f_k \exp(i\mathbf{w}_k^T \mathbf{x})$
- Consider L_2 limit of the above representation

Bochner's Theorem

A complex-valued function K on \mathbb{R}^d is the autocovariance function for a weakly stationary mean square continuous complex-valued random field on \mathbb{R}^d iff it can be represented as

$$K(\mathbf{x}) = \int_{\mathbb{R}^d} \exp(i\mathbf{w}^T \mathbf{x}) F(d\mathbf{w})$$

with F a positive finite measure.

When F has a density wrt Lebesgue measure, we have the spectral density f and

$$f(\mathbf{w}) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \exp(-i\mathbf{w}^T \mathbf{x}) K(\mathbf{x}) d\mathbf{x}$$

For isotropic random fields

- By Bochner's Theorem, for a weakly isotropic complex-valued random field Z on \mathbb{R}^d , there exists a positive finite measure F such that

$$K(|\mathbf{x}|) = \int_{\mathbb{R}^d} \exp(i\mathbf{w}^T \mathbf{x}) F(d\mathbf{w})$$

- Note $K(r) = \int_{\partial b_d} K(r|\mathbf{x}|) U(d\mathbf{x})$ for U uniform measure on ∂b_d

⇒

$$\begin{aligned} K(r) &= \int_{\partial b_d} \left\{ \int_{\mathbb{R}^d} \exp(ir\mathbf{w}^T \mathbf{x}) F(d\mathbf{w}) \right\} U(d\mathbf{x}) \\ &= \int_{\mathbb{R}^d} \left\{ \int_{\partial b_d} \cos(r\mathbf{w}^T \mathbf{x}) U(d\mathbf{x}) \right\} F(d\mathbf{w}) \end{aligned}$$

For isotropic random fields cont'd

- On the other hand,

$$\int_{\partial b_d} \cos(r\mathbf{w}^T \mathbf{x}) U(\mathbf{d}\mathbf{x}) = \Gamma(d/2) \left(\frac{2}{r|\mathbf{w}|}\right)^{(d-2)/2} J_{(d-2)/2}(r|\mathbf{w}|)$$

(J_ν : the ordinary Bessel function)

⇒

$$K(r) = 2^{(d-2)/2} \Gamma(d/2) \int_0^\infty (ru)^{-(d-2)/2} J_{(d-2)/2}(ru) dG(u)$$

for G nondecreasing, bounded on $[0, \infty)$, $G(0) = 0$
: Hankel transform of order $(d-1)/2$ of G

- In fact, this is if and only if

For isotropic random fields

- It is difficult to verify if any given function can be written in the Hankel transform of a function G satisfying the above condition
- A continuous isotropic covariance function
 - in \mathbb{R}^3 : $K(r) = \int_0^\infty (ru)^{-1} \sin(ru) dG(u)$
 - in “every” dimension: $K(r) = \int_0^\infty \exp(-r^2 u^2) dG(u)$
- **Inversion formula:** if $\int_0^\infty r^{d-1} |K(r)| dr < \infty$, there exists a nonnegative function f with $\int_0^\infty u^{d-1} f(u) du < \infty$:

$$f(u) = (2\pi)^{-d/2} \int_0^\infty (ur)^{-(d-2)/2} J_{(d-2)/2}(ur) r^{d-1} K(r) dr$$

Some examples of continuous isotropic autocovariance function

- Matérn class: $f(u) = \frac{2^{\nu-1} \phi \Gamma(\nu + \frac{d}{2}) \alpha^{2\nu}}{\pi^{d/2} (\alpha^2 + u^2)^{\nu+d/2}}$ in the Inversion formula



$$K(d) = \frac{\alpha}{2^{\nu-1} \Gamma(\nu)} \left(\frac{d}{\beta}\right)^{\nu} \mathcal{K}_{\nu}\left(\frac{d}{\beta}\right), \quad d = |\mathbf{s}_1 - \mathbf{s}_2|$$

- \mathcal{K}_{ν} is the modified Bessel function of the second kind of order ν
- ◆ Matérn class is **valid** in \mathbb{R}^p for all $p \in \mathbb{N}$

Some examples of continuous isotropic autocovariance function

- Spherical model: $K(r) = c(1 - \frac{3}{2\rho}r + \frac{1}{2\rho^3}r^3)$ for $r \leq \rho$ and zero everywhere else
 - Valid up to 3 dimension
 - Spectral density has oscillation at high frequencies
 - Spectral density of $K(r) = \sigma(\alpha - |r|)_+$: $f(w) = \sigma \frac{1 - \cos(\alpha w)}{\pi w^2}$

Smoothness of Matérn process

- ◆ The larger ν is, the smoother the resulting Matérn field is
- The Matérn field is at least m times mean square differentiable at the origin iff $\nu > m$:

$$K(d) =$$

$$\begin{cases} \sum_{j=0}^m a_j d^{2j} - \frac{\pi\alpha}{\Gamma(2\nu+1)\sin(\nu\pi)} d^{2\nu} + O(d^{2m+2}), & \text{if } m < \nu < m+1 \\ \sum_{j=0}^m b_j d^{2j} + \frac{2(-1)^m\alpha}{(2m+2)!} d^{2m+2} \log(d) + O(d^{2m+2}), & \text{if } \nu = m+1, \end{cases}$$

as $d \downarrow 0$, for appropriate constants a_j and b_j , $j = 1, \dots, m$, depending on α , ν , and β

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Non-Bayesian estimation of covariance

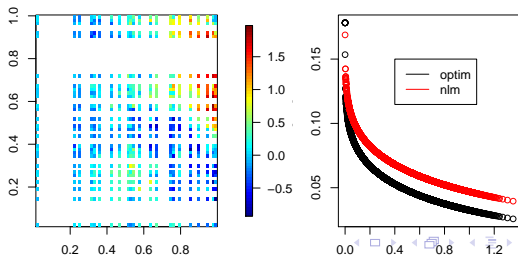
- I will only discuss likelihood methods
- Consider $Z(\mathbf{x}) = \mathbf{m}(\mathbf{x})^T \boldsymbol{\beta} + \epsilon(\mathbf{x})$ with $\text{Cov}\{\epsilon(\mathbf{x}), \epsilon(\mathbf{y})\} = K_\theta(\mathbf{x}, \mathbf{y})$
- We maximize the loglikelihood of $\mathbf{Z} = (Z(\mathbf{x}_1), \dots, Z(\mathbf{x}_n)) \sim N(M\boldsymbol{\beta}, K(\theta))$
- We may use REML (Restricted maximum likelihood estimation): maximize the loglikelihood of $\mathbf{Y} = \{I - M(M^T M)^{-1} M^T\} \mathbf{Z}$ instead of \mathbf{Z}

Some remarks on numerical optimization

- There are R packages that provide functions for maximum likelihood estimation of covariance models (but you have to be careful using them!)
- For general covariance models, I suggest to write your own likelihood function and maximize using functions such as *optim* or *nlm*
- What you get from the functions (especially *optim*) may not be “what you want”!
- Use the two functions interchangeably, try various starting points, and check Hessians!

A simple example

- I created a mean zero Gaussian random field on $[0, 1] \times [0, 1]$ with Matérn covariance structure and some nonstationarity to it
- I fitted mean zero Gaussian model with Matérn covariance structure
- Both optim and nlm claimed proper convergence and the loglikelihood values are given 660.2102 and 660.2566, respectively

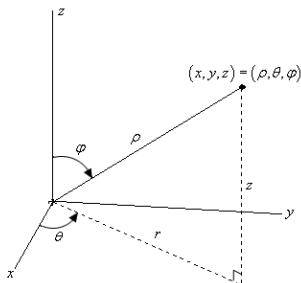


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On the surface of a sphere...

- Suppose $Z(\varphi, \theta)$ is a stochastic process on \mathcal{S}^2 ($\rho = 1$)



with mean zero and homogeneous covariance structure

- If we use a Matérn class with ϕ **distance** between \mathbf{s}_1 and \mathbf{s}_2 :

$$K(\phi) = \frac{\alpha}{2^{\nu-1} \Gamma(\nu)} \left(\frac{\phi}{\beta}\right)^{\nu} \mathcal{K}_{\nu} \left(\frac{\phi}{\beta}\right)$$

On the surface of a sphere...

- ◆ Two distances on the surface of a sphere:

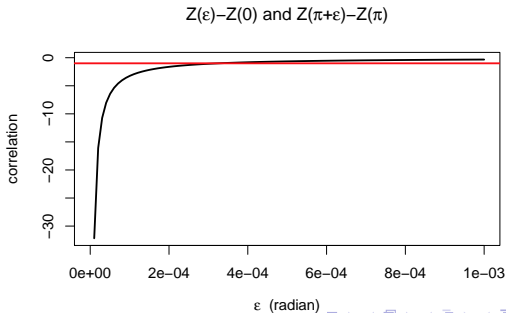
chordal vs **great circle** distance

$$d = 2R \sin(\phi/2)$$

- With chordal distance, there is no difference between covariance model on the surface of a sphere and covariance model in Euclidean distance

On the surface of a sphere...

- ◆ Matérn class is positive definite if and only if $\nu \leq 0.5$ with great circle distance on 1,2,3 dimensional spheres (Gneiting 2013)
- Interesting counter example:
 - $Z(s)$, $s \in \mathcal{S}^1$
 - Z is mean zero and its covariance function is a Gaussian covariance function ($\text{Cov}\{Z(s), Z(t)\} = K(|s - t|) = e^{-|s - t|^2}$)



What has been done so far?

This is by no means a complete list!

- 1 “Smooth” parametric covariance models on a sphere
 - Du, Ma and Li (2013, *Mathematical Geoscience*)
 - Guinness and Fuentes (2013, *preprint*)
 - Heaton, Katzfuss, Berrett, Nychka (2014, *Environmetrics*)
 - Jeong and Jun (2013, *preprint*)
- 2 Nonstationary covariance models on a sphere (univariate and multivariate)
 - Jun and Stein (2007, 2008), Jun (2011, 2014)
 - ...
- 3 Gaussian Markov Random Field models
- 4 ...

Thank you!

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